



**UNIVERSITÀ DEGLI STUDI
DELLA BASILICATA**

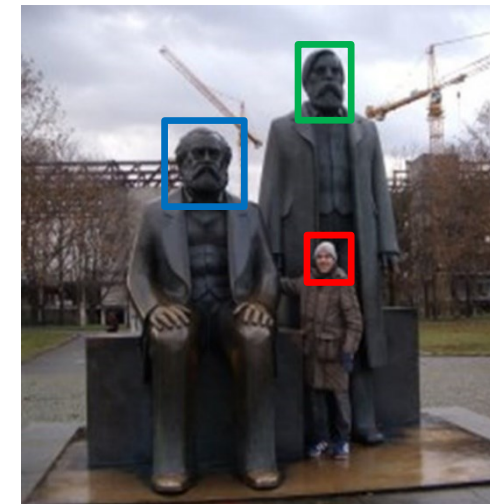
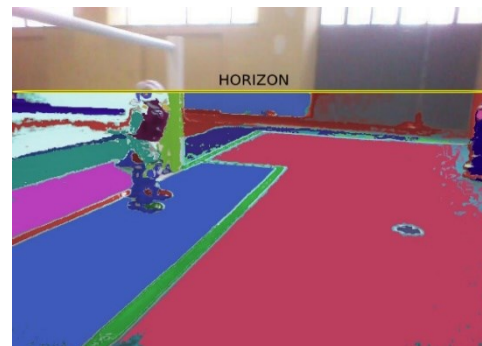
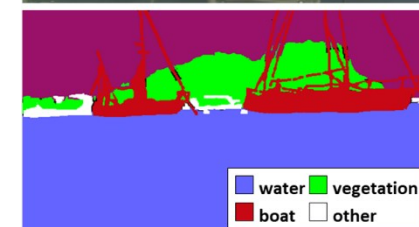
*Corso di Sistemi Informativi
A.A. 2018/19*

OpenCV (Python)

Aprile 2019

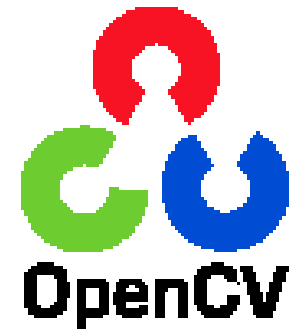


Docente
Domenico Daniele Bloisi



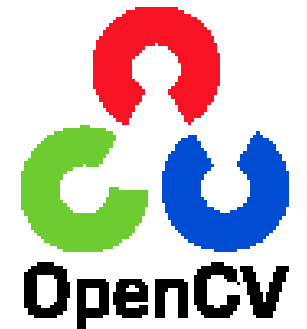
OpenCV

- OpenCV (Open Source Computer Vision Library) è una libreria software open source per la computer vision e il machine learning
- Distribuita con licenza BSD (è possibile utilizzarla per fini commerciali)
- Più di 2500 algoritmi disponibili
- Più di 47000 utenti nella community
- Più di 14 milioni di download



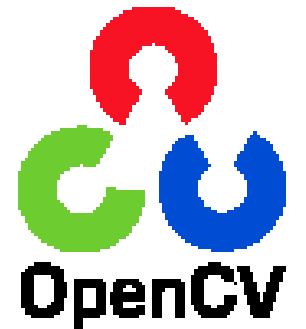
OpenCV

- Può essere utilizzata con C++, Python, Java e MATLAB
- Può essere installata su Windows, Linux, Android e Mac OS
- Dispone di interface per CUDA e OpenCL
- Viene usata da Google, Yahoo, Microsoft, Intel, IBM, Sony, Honda, Toyota



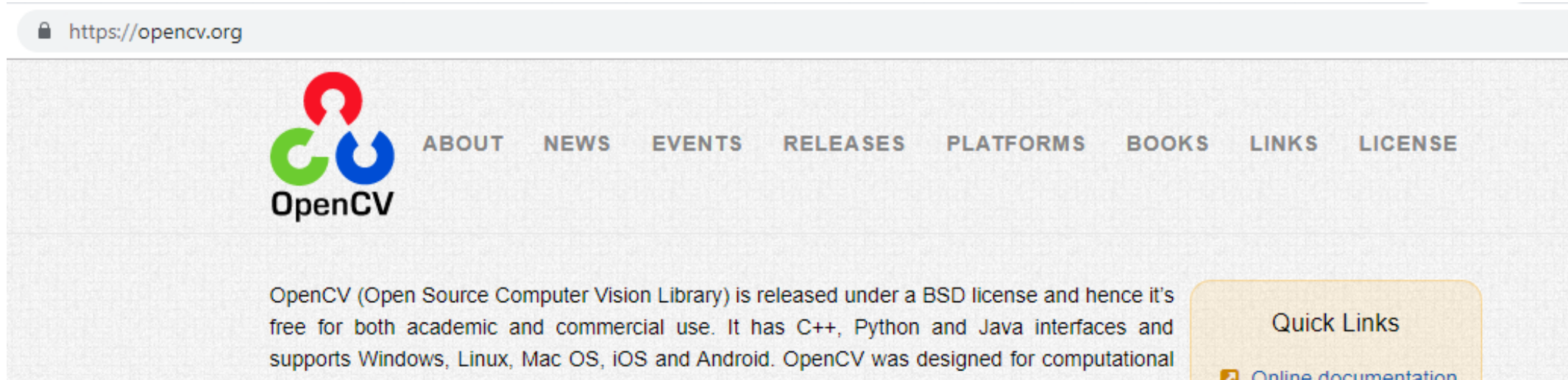
OpenCV - storia

- OpenCV was started at Intel in 1999 by **Gary Bradsky**, and the first release came out in 2000. **Vadim Pisarevsky** joined Gary Bradsky to manage Intel's Russian software OpenCV team.
- In 2005, OpenCV was used on Stanley, the vehicle that won the 2005 DARPA Grand Challenge.
- Later, its active development continued under the support of Willow Garage with Gary Bradsky and Vadim Pisarevsky leading the project.



OpenCV - links

- Home: <https://opencv.org/>
- Documentatation: <https://docs.opencv.org/>
- Q&A forum: <http://answers.opencv.org>
- GitHub: <https://github.com/opencv/>

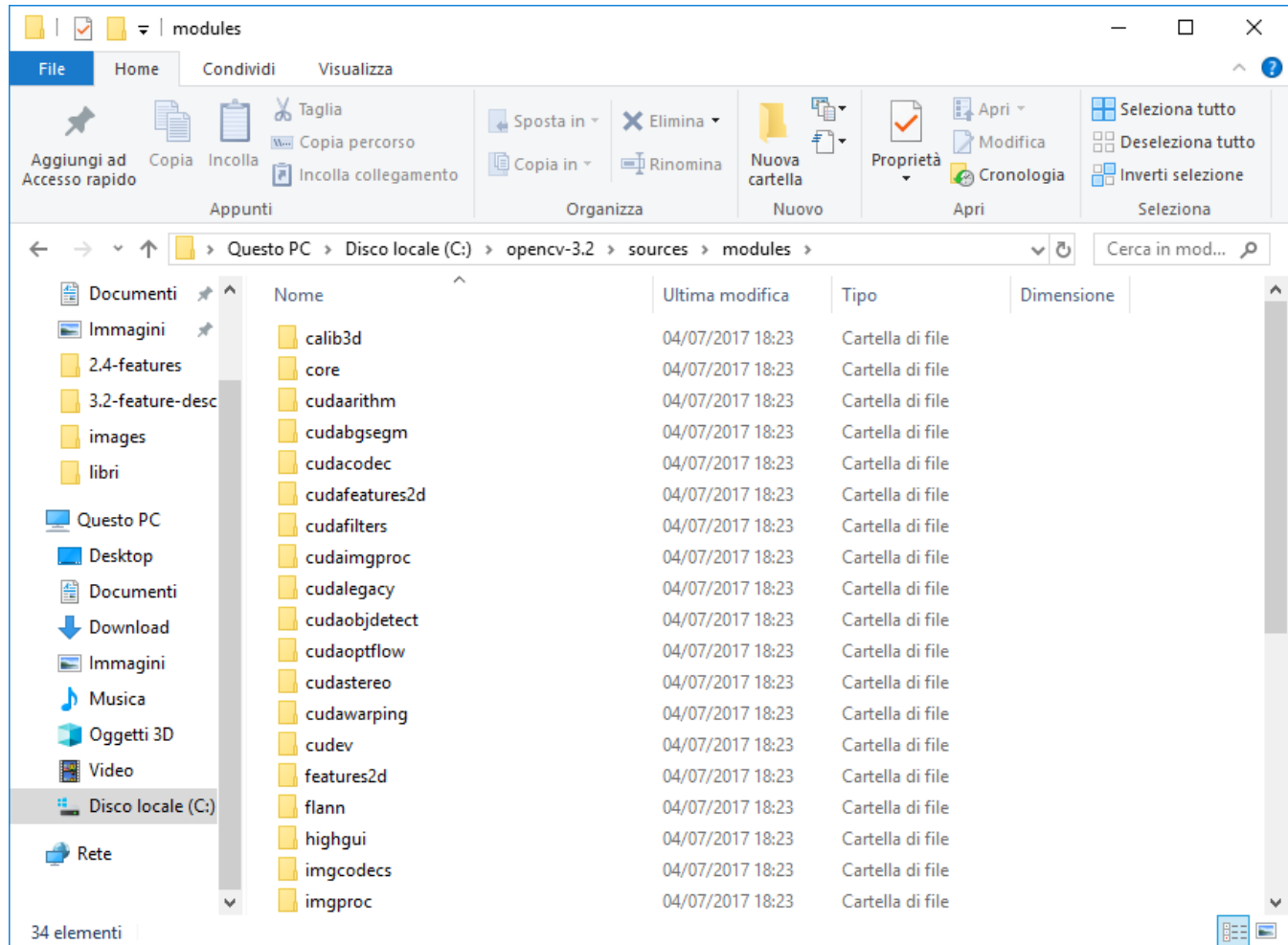


OpenCV - moduli

OpenCV ha una struttura **modulare**

I principali moduli sono:

- core
- imgproc
- video
- calib3d
- features2d
- objdetect
- highgui



OpenCV – core e imgproc

Core functionality (core)

A compact module defining basic data structures, including the dense multi-dimensional array **Mat** and basic functions used by all other modules.

Image Processing (imgproc)

An image processing module that includes linear and non-linear **image filtering**, geometrical **image transformations** (resize, affine and perspective warping, generic table-based remapping), **color space conversion**, **histograms**, and so on.

OpenCV – video e calib3d

Video Analysis (video)

A video analysis module that includes [motion estimation](#), [background subtraction](#), and [object tracking](#) algorithms.

Camera Calibration and 3D Reconstruction (calib3d)

Basic multiple-view geometry algorithms, single and stereo [camera calibration](#), object pose estimation, stereo correspondence algorithms, and elements of 3D reconstruction.

OpenCV – features2d e objdetect

2D Features Framework (features2d)

Salient [feature detectors](#), [descriptors](#), and descriptor matchers.

Object Detection (objdetect)

[Detection](#) of objects and instances of the predefined classes (for example, faces, eyes, mugs, people, cars, and so on).

OpenCV – highgui e videoio

High-level GUI (highgui)

an easy-to-use interface to [simple UI](#) capabilities.

Video I/O (videoio)

An easy-to-use interface to [video capturing and video codecs](#).

OpenCV – Python

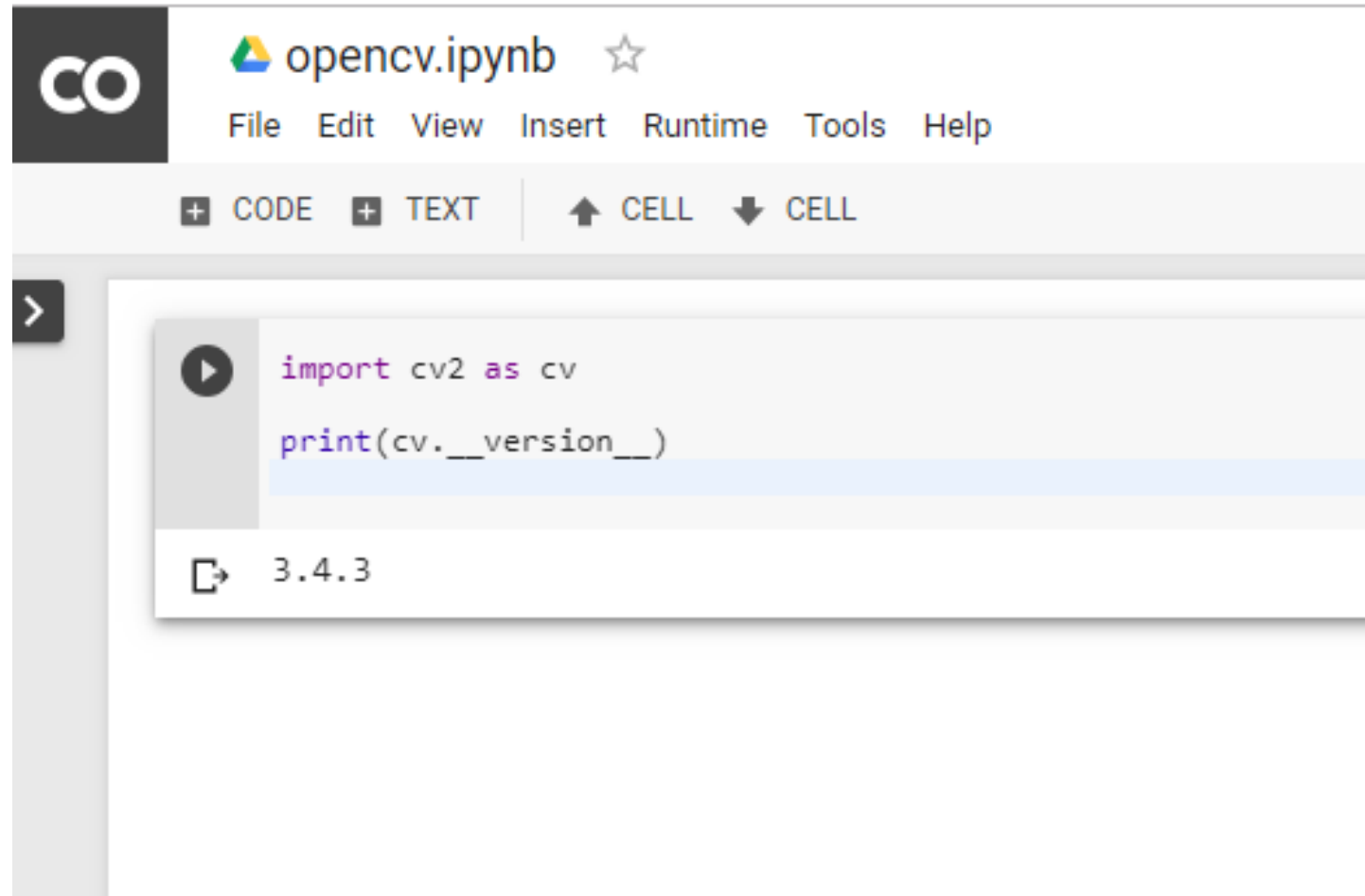
- Python is slower compared to C++ or C. Python is built for its simplicity, portability and moreover, creativity where users need to worry only about their algorithm, not programming troubles.
- Python-OpenCV is just a **wrapper** around the original C/C++ code. It is normally used for combining best features of both the languages.
Performance of C/C++ & Simplicity of Python.
- So when you call a function in OpenCV from Python, what actually runs is underlying C/C++ source.
- Performance penalty is < 4%

OpenCV Timeline

Version	Released	Reason	Lifetime
pre 1.0	2000 (first alpha)	-	6 years
1.0	2006 (ChangeLog)	maturity	3 years
2.0	2009 (ChangeLog)	C++ API	>3 years
3.0	2014	several (next level maturity, ...)	
4.0	Nov. 2018	better DNN support	

OpenCV in Colab

La versione di OpenCV attualmente disponibile in Google Colab è la 3.4.3



The screenshot shows a Google Colab notebook interface. At the top, the notebook title is "opencv.ipynb" with a star icon. Below the title is a menu bar with "File", "Edit", "View", "Insert", "Runtime", "Tools", and "Help". Underneath the menu bar are buttons for "+ CODE", "+ TEXT", "↑ CELL", and "↓ CELL". The main area of the notebook contains a code cell with the following Python code:


```
import cv2 as cv
print(cv.__version__)
```

Below the code cell, the output of the code is displayed as "3.4.3".

OpenCV 3.4.3 docs

← → ↻ <https://docs.opencv.org/3.4.3/>

Google Custom Search

 **OpenCV**

Open Source Computer Vision

[Main Page](#) [Related Pages](#) [Modules](#) [Namespaces](#) [Classes](#) [Files](#) [Examples](#) [Java documentation](#)

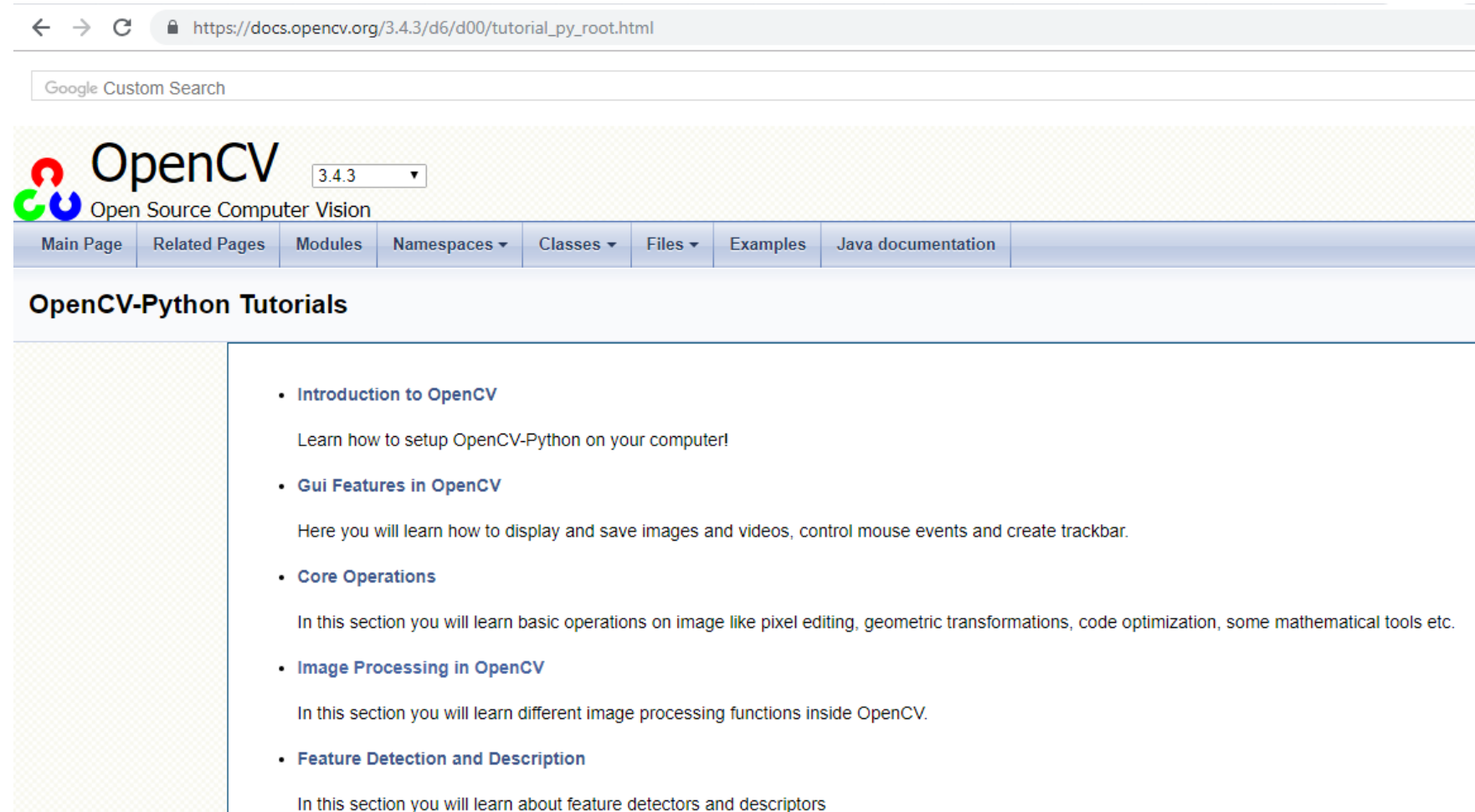
OpenCV modules

- [Introduction](#)
- [OpenCV Tutorials](#)
- [OpenCV-Python Tutorials](#)
- [OpenCV.js Tutorials](#)
- [Tutorials for contrib modules](#)
- [Frequently Asked Questions](#)
- [Bibliography](#)
- Main modules:
 - [core](#). **Core functionality**
 - [imgproc](#). **Image processing**
 - [imgcodecs](#). **Image file reading and writing**
 - [videoio](#). **Video I/O**
 - [highgui](#). **High-level GUI**
 - [video](#). **Video Analysis**
 - [calib3d](#). **Camera Calibration and 3D Reconstruction**
 - [features2d](#). **2D Features Framework**

<https://docs.opencv.org/3.4.3/>

OpenCV-Python Tutorials

OpenCV fornisce una serie di tutorial specifici per Python che possono essere utilizzati per imparare ad utilizzare la libreria attraverso esempi pratici



The screenshot shows a web browser window displaying the OpenCV Python Tutorials page. The browser's address bar shows the URL: `https://docs.opencv.org/3.4.3/d6/d00/tutorial_py_root.html`. Below the address bar is a search bar labeled "Google Custom Search". The page header features the OpenCV logo (three interlocking circles in red, green, and blue) and the text "OpenCV 3.4.3" with a dropdown menu. Below the logo is the text "Open Source Computer Vision". A navigation menu contains the following items: "Main Page", "Related Pages", "Modules", "Namespaces", "Classes", "Files", "Examples", and "Java documentation". The main content area is titled "OpenCV-Python Tutorials" and contains a list of tutorial links with brief descriptions:

- **Introduction to OpenCV**
Learn how to setup OpenCV-Python on your computer!
- **Gui Features in OpenCV**
Here you will learn how to display and save images and videos, control mouse events and create trackbar.
- **Core Operations**
In this section you will learn basic operations on image like pixel editing, geometric transformations, code optimization, some mathematical tools etc.
- **Image Processing in OpenCV**
In this section you will learn different image processing functions inside OpenCV.
- **Feature Detection and Description**
In this section you will learn about feature detectors and descriptors

Load an image in Colab

The image illustrates the steps to load an image in a Google Colab notebook. It consists of two screenshots of a notebook titled 'opencv.ipynb' with a blue arrow pointing from the first to the second.

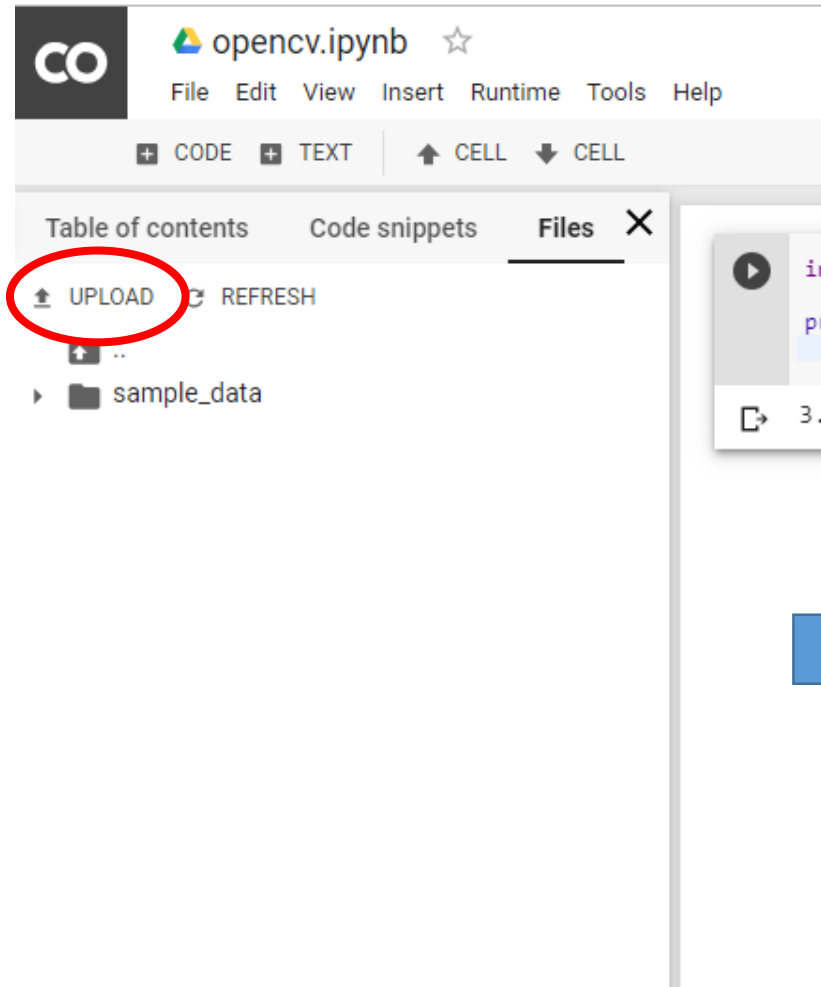
Left Screenshot: Shows a code cell with the following code:

```
import cv2 as cv
print(cv.__version__)
```

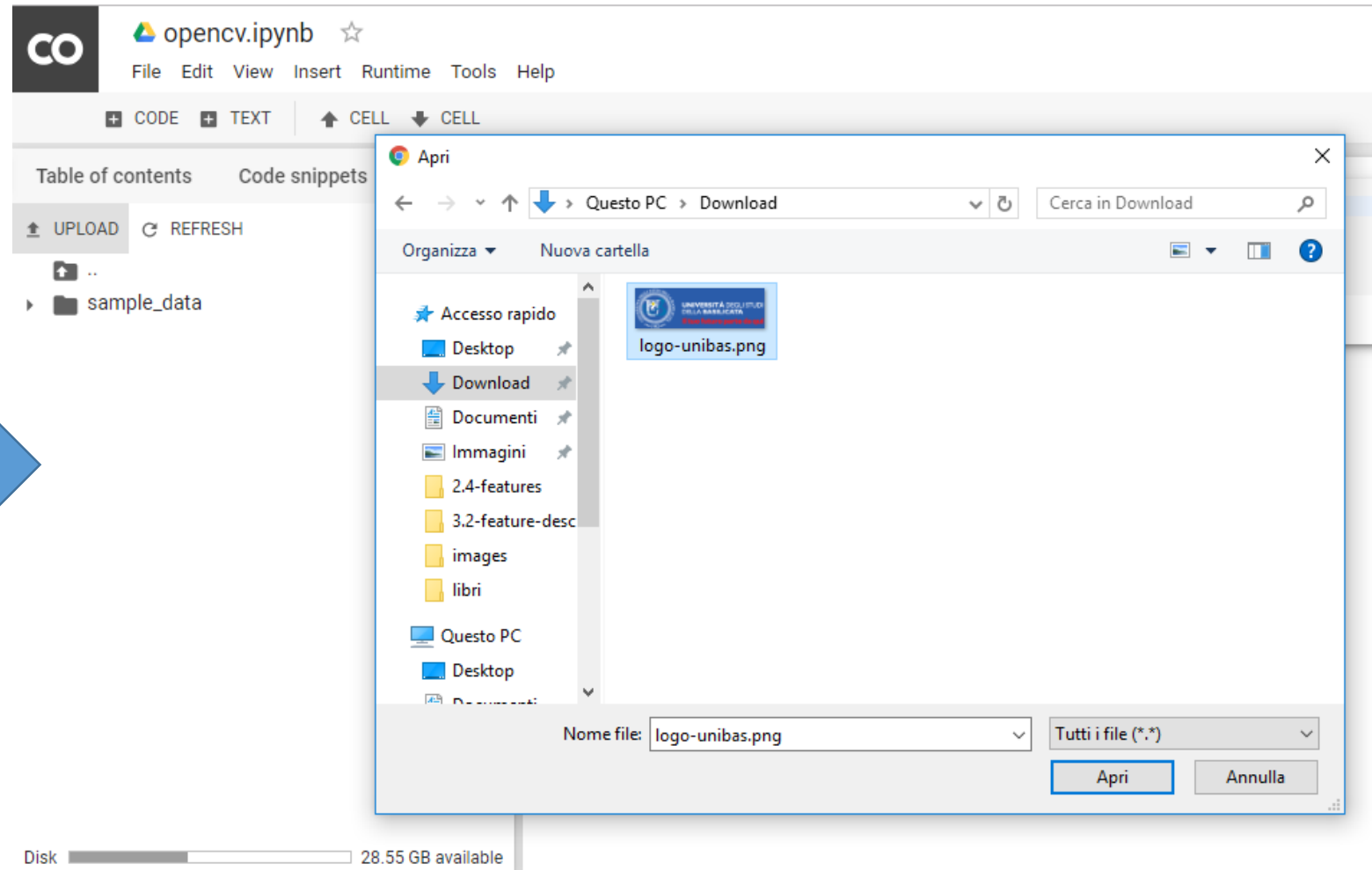
The output of the cell is '3.4.3'. A red circle highlights the right-pointing arrow icon in the left sidebar, which is used to open the file manager.

Right Screenshot: Shows the same code cell and output. A red circle highlights the 'Files' tab in the file manager interface, which is open and displays a file tree with 'sample_data'.

Load an image in Colab



<http://portale.unibas.it/contents/instance1/images/logo-unibas.png>



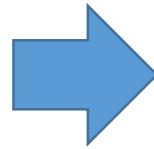
Load an image in Colab

```
print(cv.__version__)
```

3.4.3

Reminder, uploaded files will get deleted when this runtime is recycled.
[More info](#)

OK



opencv.ipynb ☆

File Edit View Insert Runtime Tools Help

+ CODE + TEXT ↑ CELL ↓ CELL

Table of contents Code snippets Files X

↑ UPLOAD ↻ REFRESH

- ..
- sample_data
- logo-unibas.png

```
import cv2 as cv
print(cv.__version__)
```

3.4.3

Disk 28.55 GB available

Read an image

```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png')
plt.imshow(img)
plt.xticks([]), plt.yticks([]) # to hide tick values on X and Y axis
plt.show()
```



warning

Color image loaded by OpenCV is in **BGR** mode. But Matplotlib displays in RGB mode. So color images will not be displayed correctly in Matplotlib if image is read with OpenCV.

Source image



Images are NumPy arrays

Images in
OpenCV-Python
are NumPy
arrays

```
▶ import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png')

print(type(img))
print(img.ndim)
print(img.shape)

plt.imshow(img)
plt.xticks([]), plt.yticks([]) # to hide tick values on X and Y axis
plt.show()
```

```
↳ 3
(97, 312, 3)
<class 'numpy.ndarray'>
```



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RGB visualization in Matplotlib

```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

print(type(img))
print(img.ndim)
print(img.shape)

img_rgb = img[:, :, ::-1]

plt.imshow(img_rgb)
plt.xticks([]), plt.yticks([]) # to hide tick values on X and Y axis
plt.show()
```

```
<class 'numpy.ndarray'>
3
(97, 312, 3)
```



Accessing and Modifying pixel values



```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

# accessing pixel in position (50,100)
px = img[50,100] #[y-value, x-value]
print(px)

# accessing only blue pixel
blue = img[50,100,0]
print(blue)

img[50,100] = [255,255,255]
print(img[50,100])
```

```
↳ [170  92  42]
   170
   [255 255 255]
```

warning

Numpy is a optimized library for fast array calculations. So simply accessing each and every pixel values and modifying it will be very slow and it is discouraged.

item e itemset



```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

# accessing only blue pixel
blue = img.item(50,100,0)
print(blue)

img.itemset((50,100,0),255)
print(img[50,100])
```



```
170
[255  92  42]
```

Accessing Image Properties

number of rows, columns, and channels (if image is color)

```
[28] print(img.shape)
```

```
↳ (97, 312, 3)
```

Total number of pixels

```
[29] print(img.size)
```

```
↳ 90792
```

Image datatype

```
▶ print(img.dtype)
```

```
↳ uint8
```

Image ROI

```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

logo = img[0:98,0:98]
img[0:98, 100:198] = logo
img[0:98, 200:298] = logo

img_rgb = img[:, :, ::-1]

plt.imshow(img_rgb)
plt.xticks([]), plt.yticks([]) # to hide tick values on X and Y axis
plt.show()
```



Changing Color-space

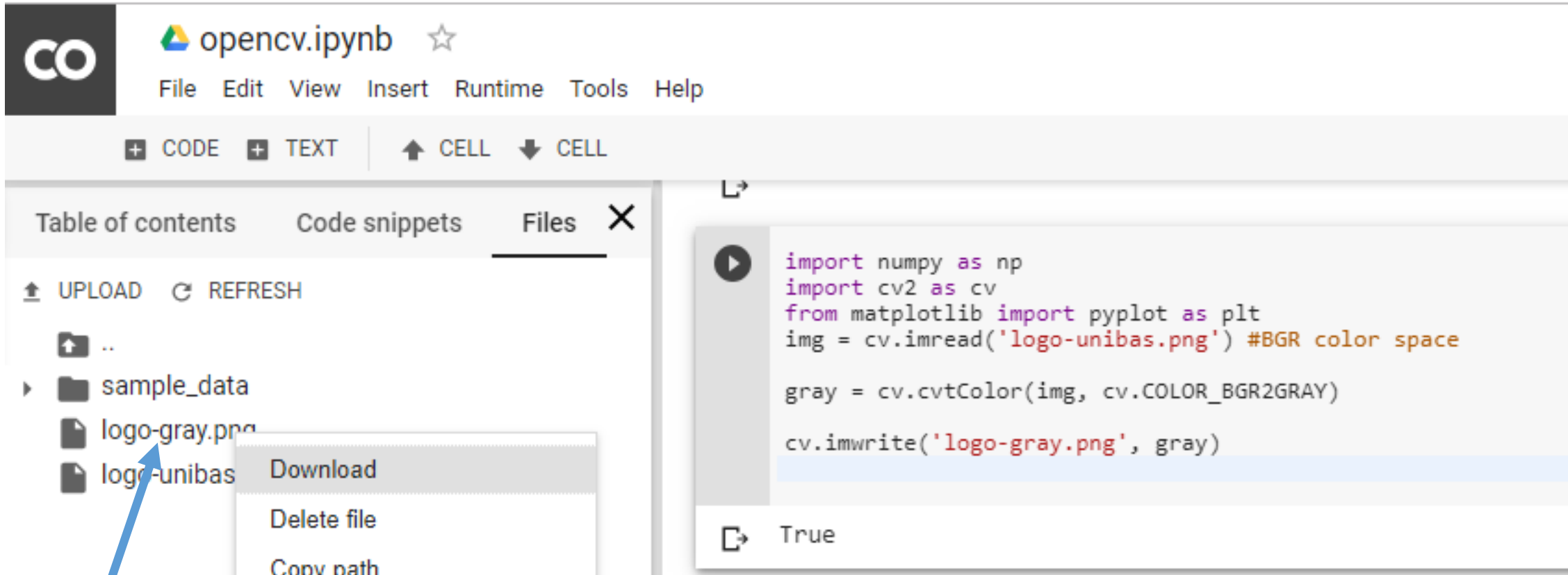
```
▶ import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

gray = cv.cvtColor(img, cv.COLOR_BGR2GRAY)

cv.imwrite('logo-gray.png', gray)
```

☞ True

Grayscale conversion



The screenshot shows the OpenCV Jupyter Notebook interface. The top bar includes the 'CO' logo, the title 'opencv.ipynb', and a star icon. Below this is a menu bar with 'File', 'Edit', 'View', 'Insert', 'Runtime', 'Tools', and 'Help'. The main area is divided into a file explorer on the left and a code editor on the right. The file explorer shows a directory structure with 'sample_data' containing 'logo-gray.png' and 'logo-unibas.png'. A right-click context menu is open over 'logo-unibas.png', showing options: 'Download', 'Delete file', and 'Copy path'. A blue arrow points from the text 'tasto destro del mouse' to the 'logo-unibas.png' file. The code editor contains the following Python code:

```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

gray = cv.cvtColor(img, cv.COLOR_BGR2GRAY)

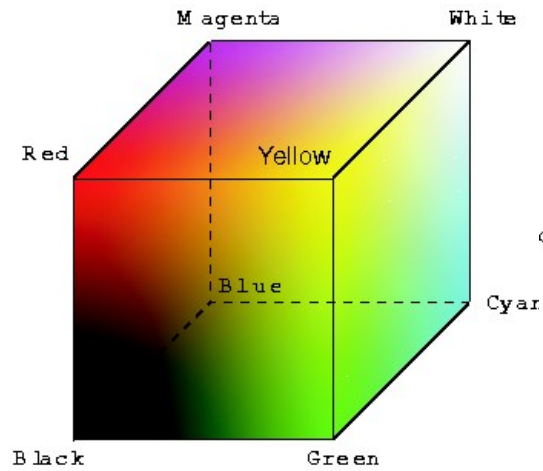
cv.imwrite('logo-gray.png', gray)
```

Below the code editor, the output 'True' is displayed.

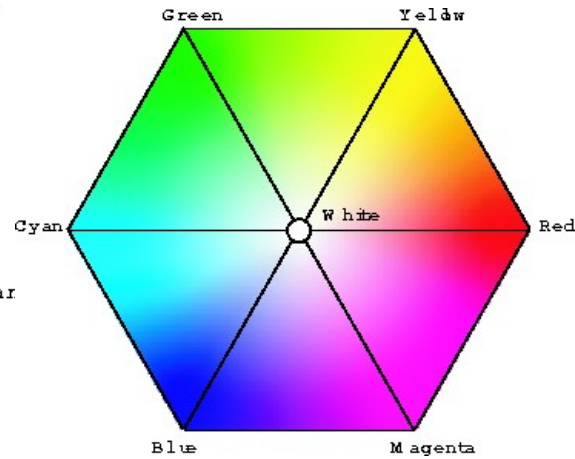
tasto
destro del
mouse



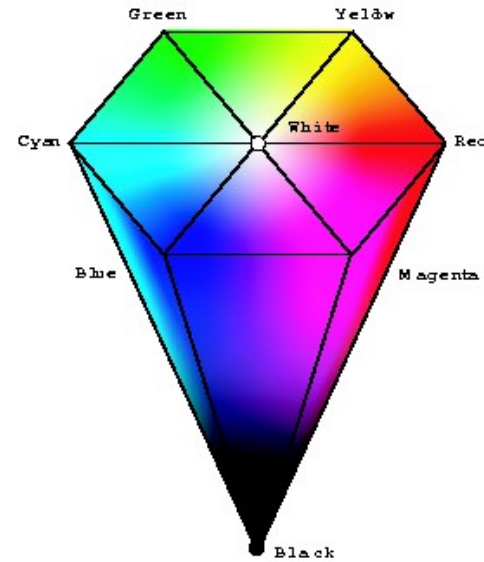
HSV color-space



RGB cube



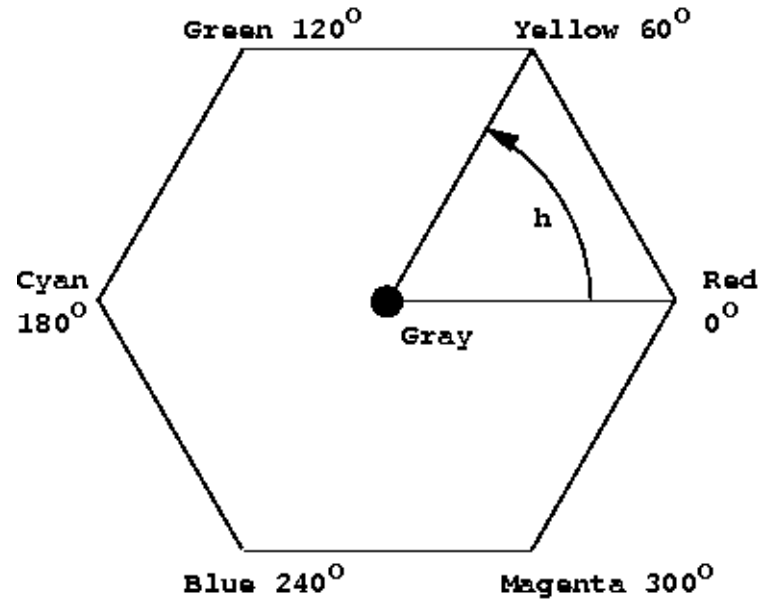
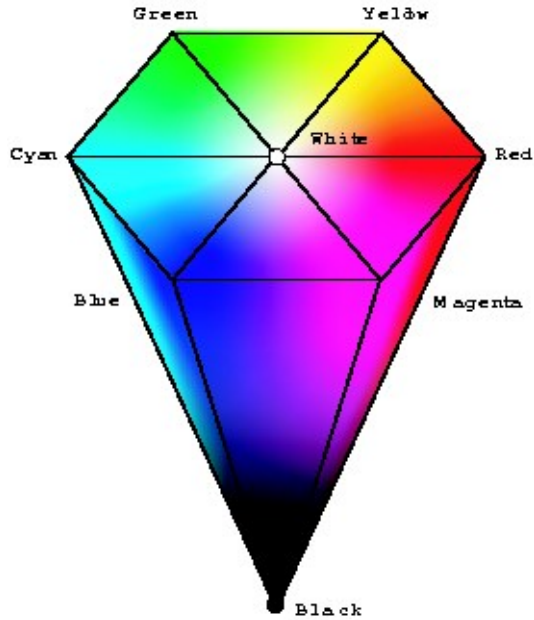
HSV top view



HSV cone

HSV is a projection of the RGB space

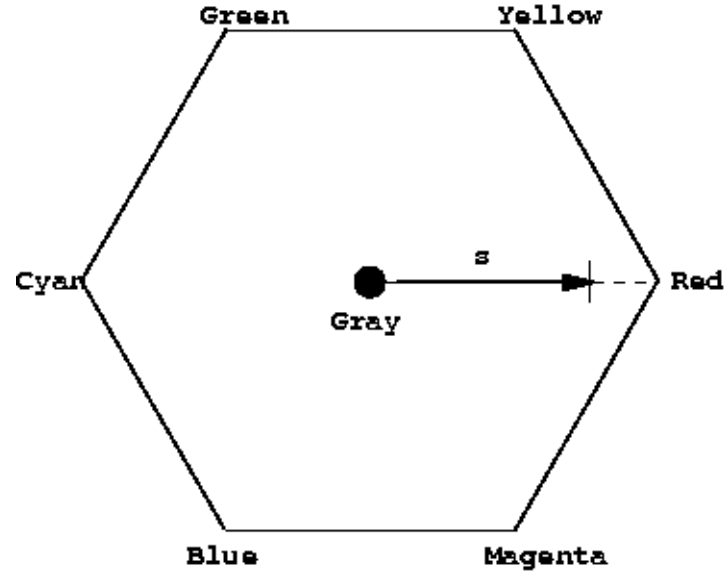
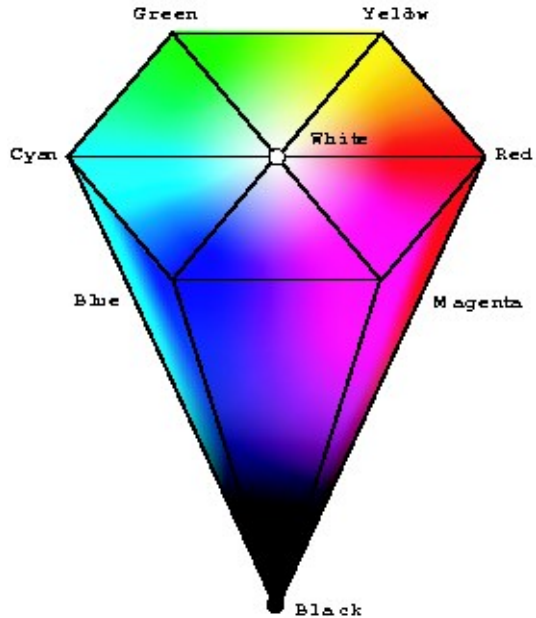
Hue



Hue, an angular measure (0 ... 360)

Hue range is [0,179] in OpenCV

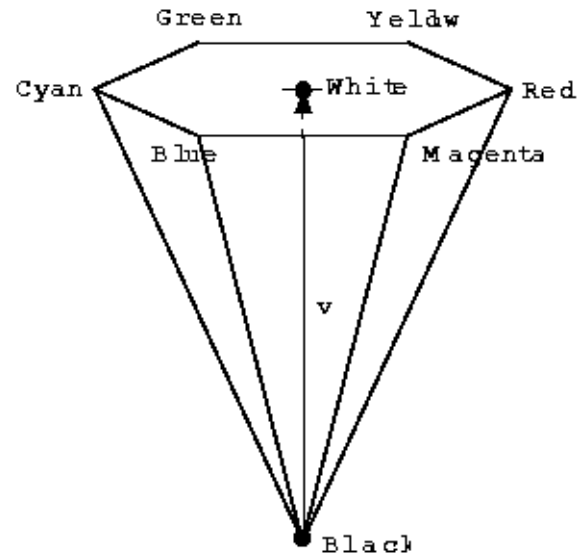
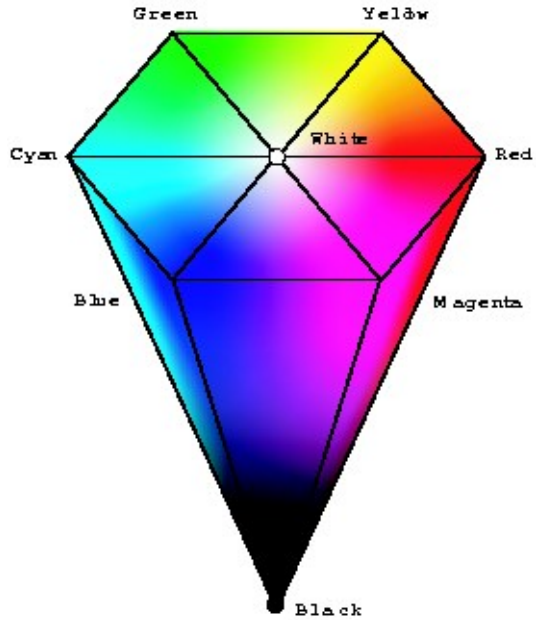
Saturation



Saturation, a fractional measure (0.0 ... 1.0)

Saturation range is [0,255] in OpenCV

Value



Value, a fractional measure (0.0 ... 1.0)

Value range is [0,255] in OpenCV

HSV conversion

```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

hsv = cv.cvtColor(img, cv.COLOR_BGR2HSV)

plt.imshow(hsv)
plt.xticks([]), plt.yticks([]) # to hide tick values on X and Y axis
plt.show()
```



Split

```
▶ import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

hsv = cv.cvtColor(img, cv.COLOR_BGR2HSV)

h,s,v = cv.split(hsv)

plt.imshow(h)
plt.xticks([]), plt.yticks([]) # to hide tick values on X and Y axis
plt.show()
```



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Split – Saturation channel

```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

hsv = cv.cvtColor(img, cv.COLOR_BGR2HSV)

h,s,v = cv.split(hsv)

plt.imshow(s)
plt.xticks([], plt.yticks([])) # to hide tick values on X and Y axis
plt.show()
```



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Split – Value channel

```
▶ import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

hsv = cv.cvtColor(img, cv.COLOR_BGR2HSV)

h,s,v = cv.split(hsv)

plt.imshow(s)
plt.xticks([], plt.yticks([])) # to hide tick values on X and Y axis
plt.show()
```



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Merge

```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

hsv = cv.cvtColor(img, cv.COLOR_BGR2HSV)

h,s,v = cv.split(hsv)

hsv_merged = cv.merge((h,s,v))

plt.imshow(hsv_merged)
plt.xticks([], plt.yticks([])) # to hide tick values on X and Y axis
plt.show()
```



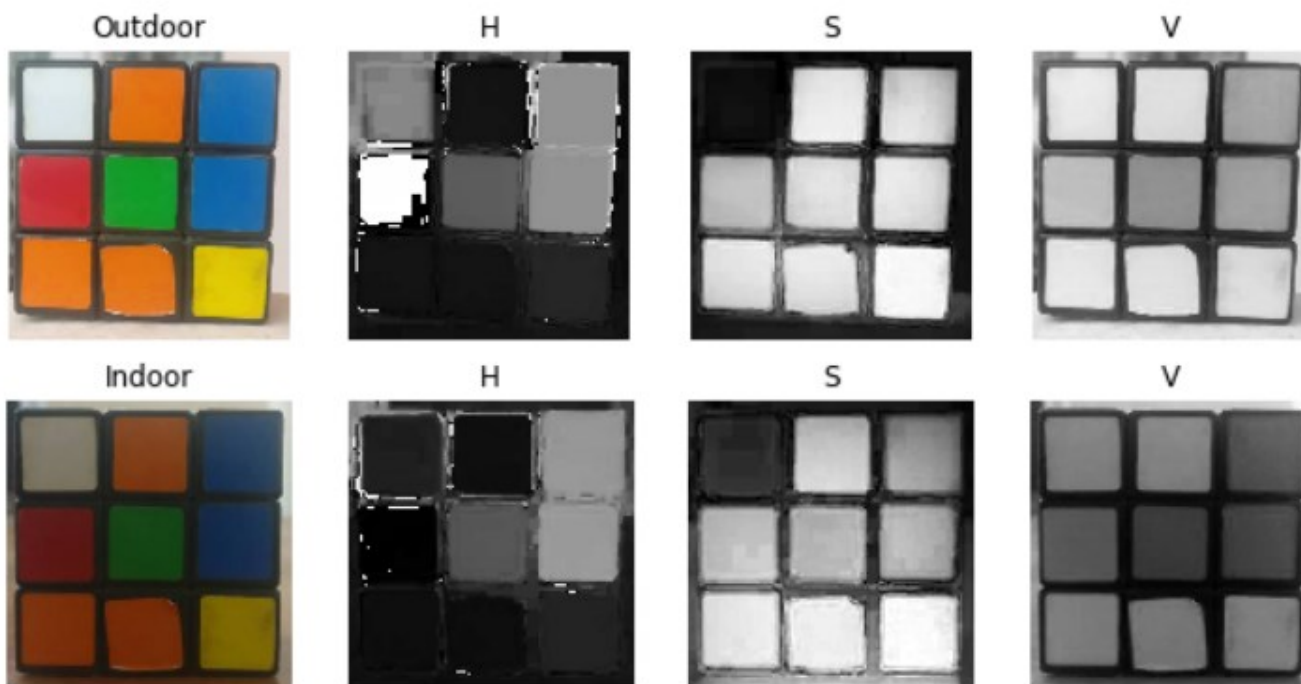
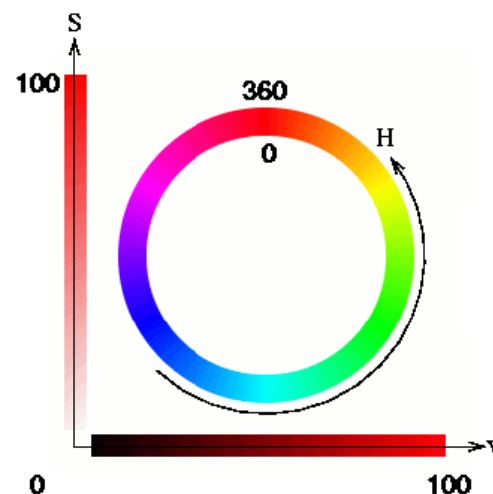
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HSV color space

The HSV color space has the following three components

1. H – Hue (Dominant Wavelength)
2. S – Saturation (Purity/shades of the color)
3. V – Value (Intensity)



Observations

- The H Component is very similar in both the images which indicates the color information is intact even under illumination changes
- The S component is also very similar in both images
- The V Component captures the amount of light falling on it thus it changes due to illumination changes

Read an image from URL

```
import numpy as np
import cv2 as cv

import matplotlib.pyplot as plt
import urllib.request

url = "http://portale.unibas.it/contents/instance1/images/logo-unibas.png"
url_response = urllib.request.urlopen(url)

numpy_img = np.array(bytearray(url_response.read()), dtype=np.uint8)
img = cv.imdecode(numpy_img, -1)

plt.imshow(img)
plt.xticks([], plt.yticks([])) # to hide tick values on X and Y axis
plt.show()
```



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Il tuo futuro parte da qui

Read an image from URL

```
import cv2 as cv
import numpy as np
import matplotlib.pyplot as plt
import urllib.request

url = "http://portale.unibas.it/contents/instance1/images/logo-unibas.png"

url_response = urllib.request.urlopen(url)
numpy_img = np.array(bytearray(url_response.read()), dtype=np.uint8)
img = cv.imdecode(numpy_img, -1)

rgb = cv.cvtColor(img, cv.COLOR_BGR2RGB)

plt.axis('off')
plt.imshow(rgb)
plt.show()
```





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OpenCV (Python)

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Docente
Domenico Daniele Bloisi

