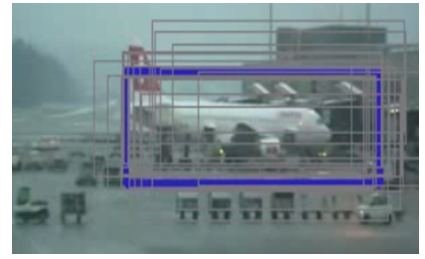
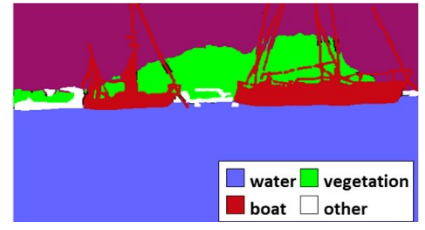


UNIVERSITÀ DEGLI STUDI DELLA BASILICATA

Corso di Sistemi Informativi
A.A. 2018/19

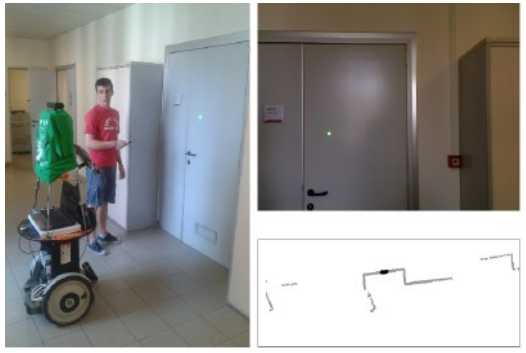
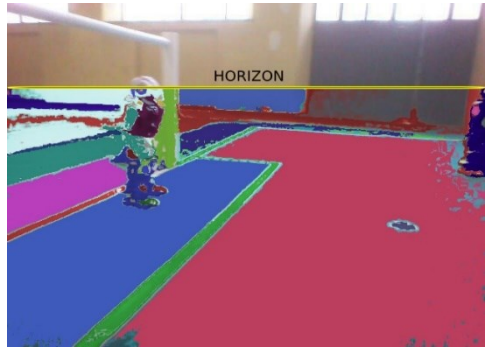
Docente
Domenico Daniele Bloisi



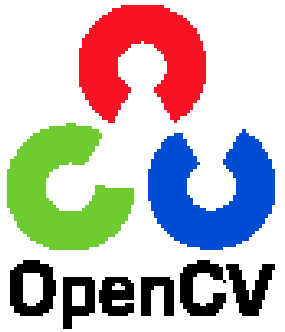
OpenCV (Python)

Aprile 2019

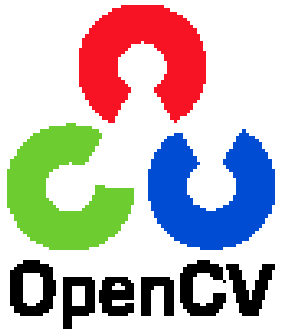

OpenCV

- OpenCV (Open Source Computer Vision Library) è una libreria software open source per la computer vision e il machine learning
- Distribuita con licensa BSD (è possibile utilizzarla per fini commerciali)
- Più di 2500 algoritmi disponibili
- Più di 47000 utenti nella community
- Più di 14 milioni di download



OpenCV

- Può essere utilizzata con C++, Python, Java e MATLAB
- Può essere installata su Windows, Linux, Android e Mac OS
- Dispone di interface per CUDA e OpenCL
- Viene usata da Google, Yahoo, Microsoft, Intel, IBM, Sony, Honda, Toyota

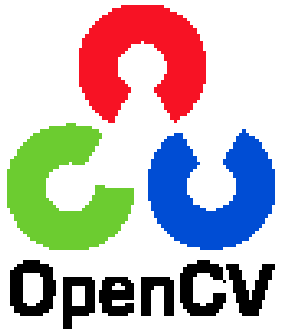


OpenCV - storia

- OpenCV was started at Intel in 1999 by **Gary Bradsky**, and the first release came out in 2000. **Vadim Pisarevsky** joined Gary Bradsky to manage Intel's Russian software OpenCV team.

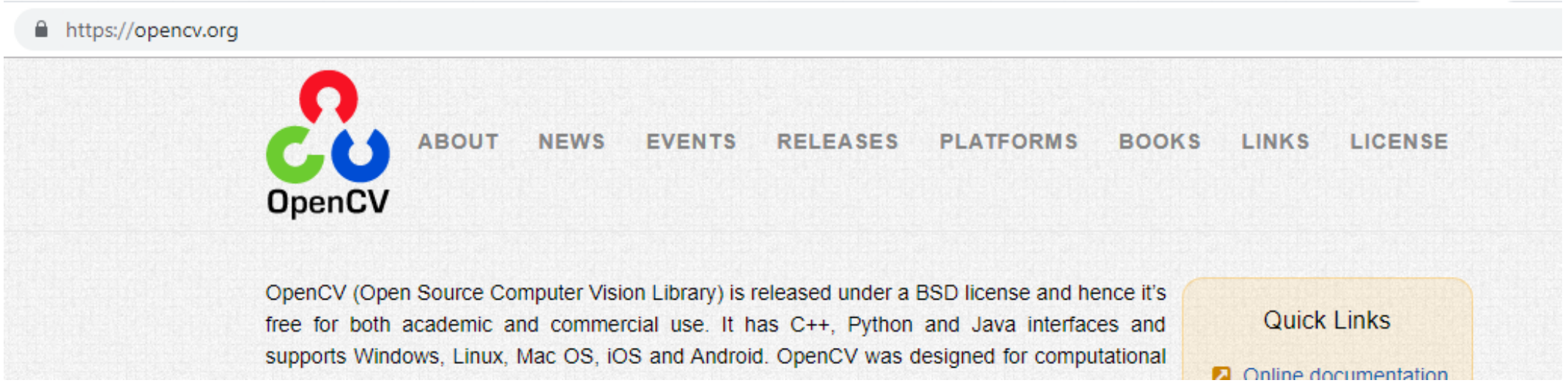
- In 2005, OpenCV was used on Stanley, the vehicle that won the 2005 DARPA Grand Challenge.

- Later, its active development continued under the support of Willow Garage with Gary Bradsky and Vadim Pisarevsky leading the project.



OpenCV - links

- Home: https://opencv.org/
- Documentatation: https://docs.opencv.org/
- Q&A forum: http://answers.opencv.org
- GitHub: https://github.com/opencv/

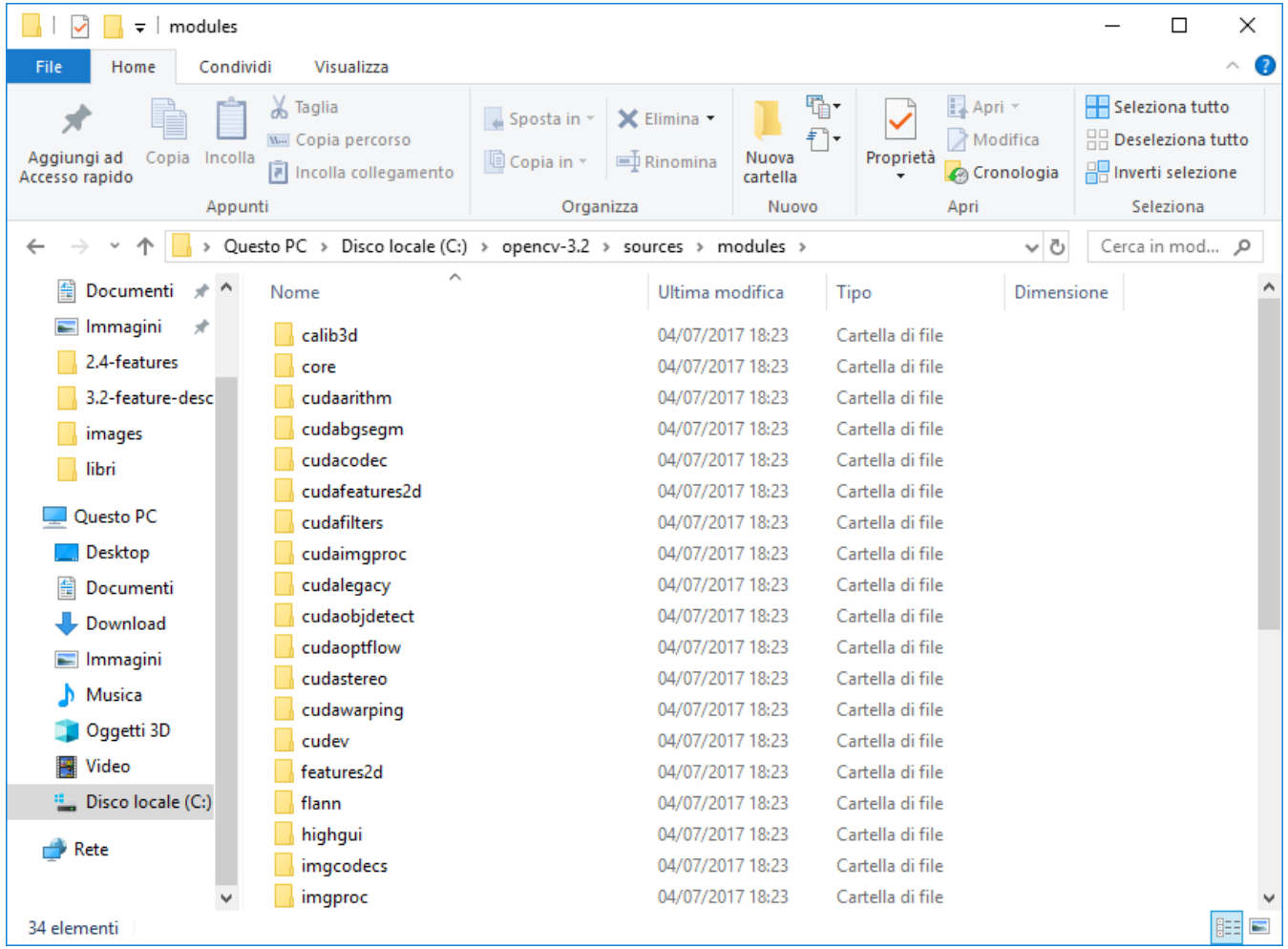


OpenCV - moduli

OpenCV ha una struttura modulare

I principali moduli sono:

- core
- imgproc
- video
- calib3d
- features2d
- objdetect
- highgui



OpenCV – core e imgproc

Core functionality (**core**)
A compact module defining basic data structures, including the dense multi-dimensional array Mat and basic functions used by all other modules.

Image Processing (**imgproc**)
An image processing module that includes linear and non-linear image filtering, geometrical image transformations (resize, affine and perspective warping, generic table-based remapping), color space conversion, histograms, and so on.

OpenCV – video e calib3d

Video Analysis (**video**)
A video analysis module that includes motion estimation, background subtraction, and object tracking algorithms.

Camera Calibration and 3D Reconstruction (**calib3d**)
Basic multiple-view geometry algorithms, single and stereo camera calibration, object pose estimation, stereo correspondence algorithms, and elements of 3D reconstruction.

OpenCV – features2d e objdetect

2D Features Framework (**features2d**)
Salient feature detectors, descriptors, and descriptor matchers.

Object Detection (**objdetect**)
Detection of objects and instances of the predefined classes (for example, faces, eyes, mugs, people, cars, and so on).

OpenCV – highgui e videoio

High-level GUI (**highgui**)
an easy-to-use interface to simple UI capabilities.

Video I/O (**videoio**)
An easy-to-use interface to video capturing and video codecs.

OpenCV – Python

- Python is slower compared to C++ or C. Python is built for its simplicity, portability and moreover, creativity where users need to worry only about their algorithm, not programming troubles.

- Python-OpenCV is just a wrapper around the original C/C++ code. It is normally used for combining best features of both the languages. Performance of C/C++ & Simplicity of Python.

- So when you call a function in OpenCV from Python, what actually run is underlying C/C++ source.

- Performance penalty is < 4%

Source: Mašinska vizija

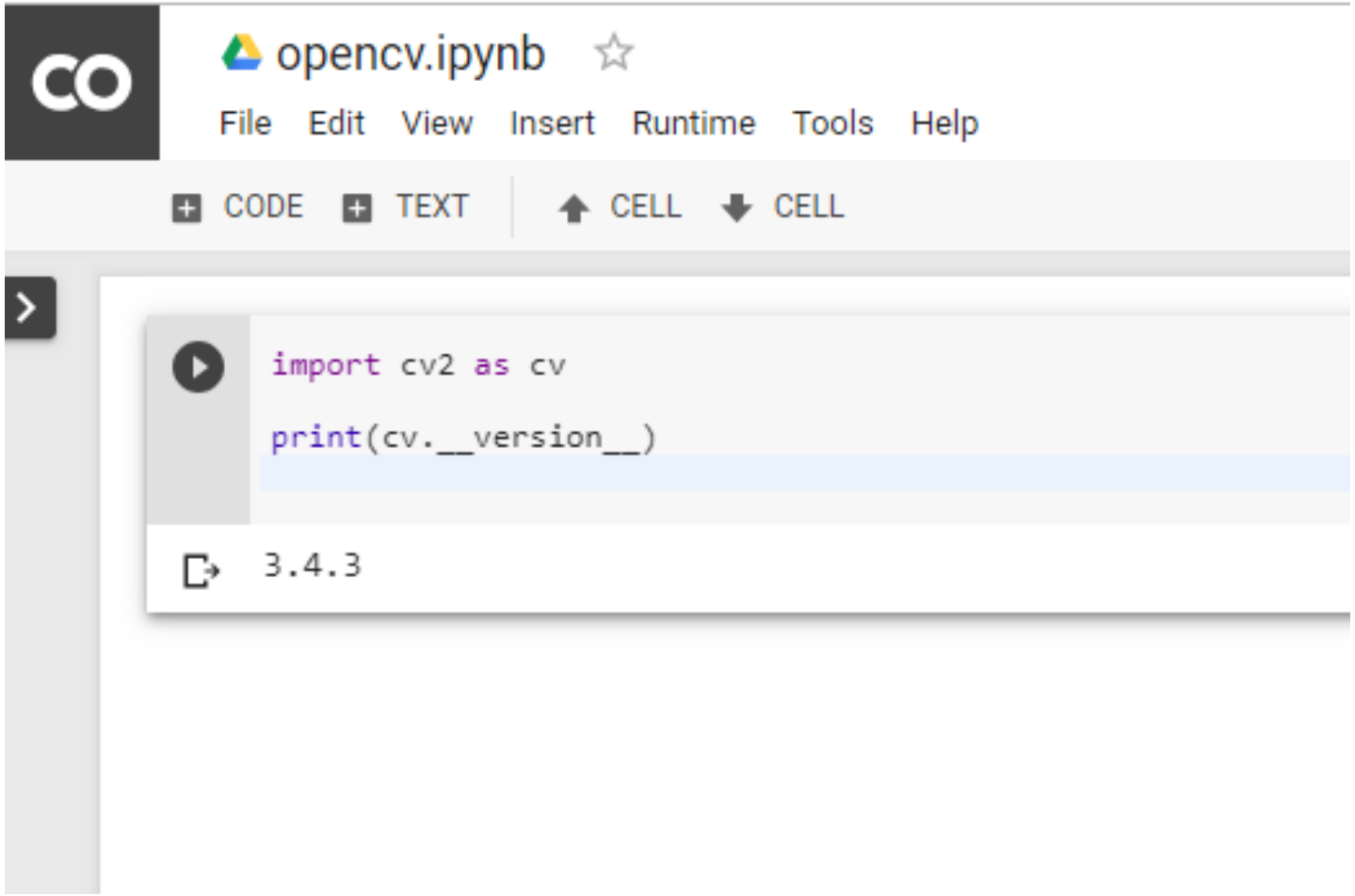
OpenCV Timeline

Version	Released	Reason	Lifetime
pre 1.0	2000 (first alpha)	-	6 years
1.0	2006 (ChangeLog)	maturity	3 years
2.0	2009 (ChangeLog)	C++ API	>3 years
3.0	2014	several (next level maturity, ...)	
4.0	**Nov. 2018**	better DNN support	

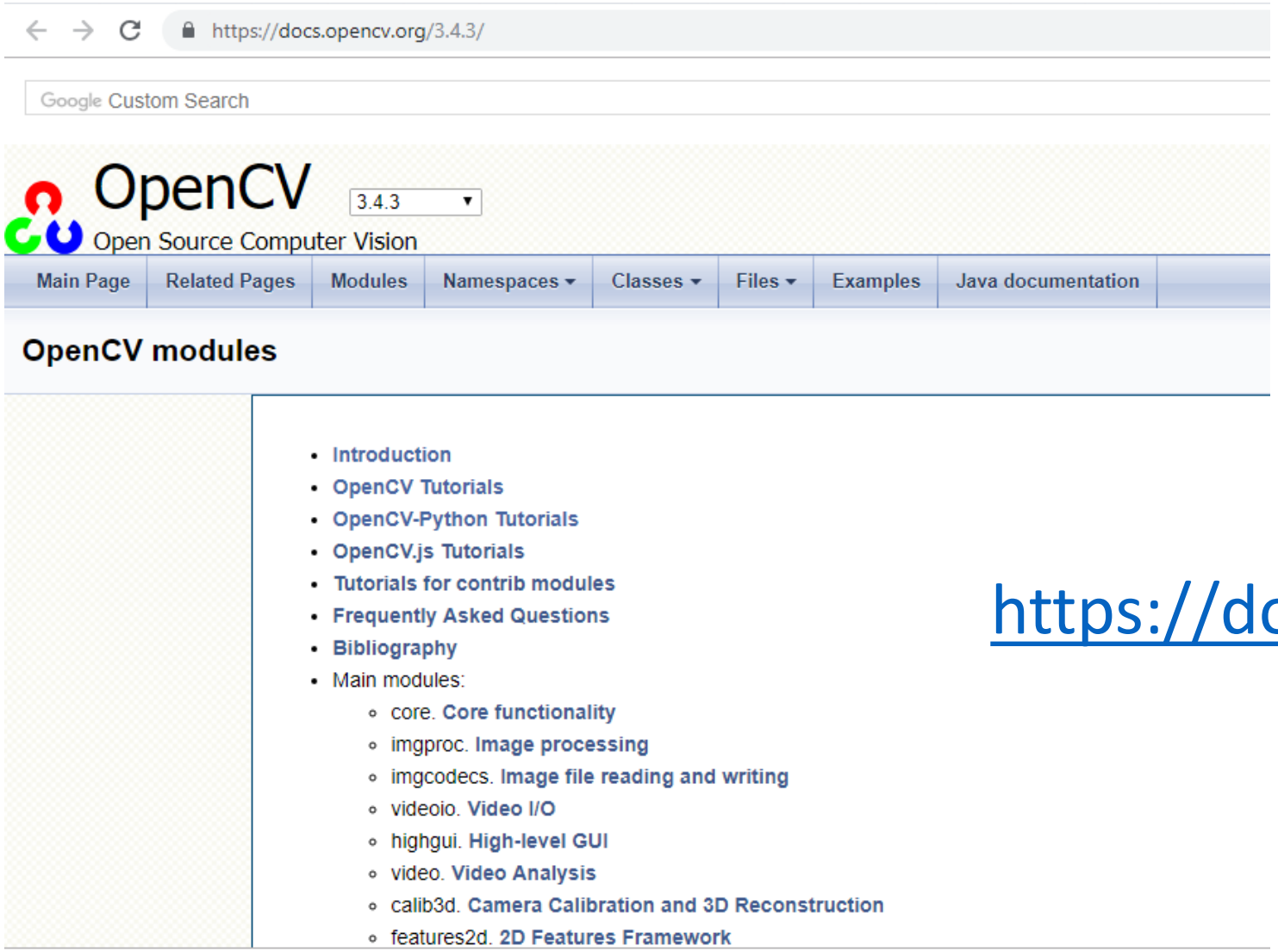
https://github.com/opencv/opencv/wiki/images/OpenCV3_0_CVPR_2014.pptx

OpenCV in Colab

La versione di OpenCV attualmente disponibile in Google Colab è la 3.4.3



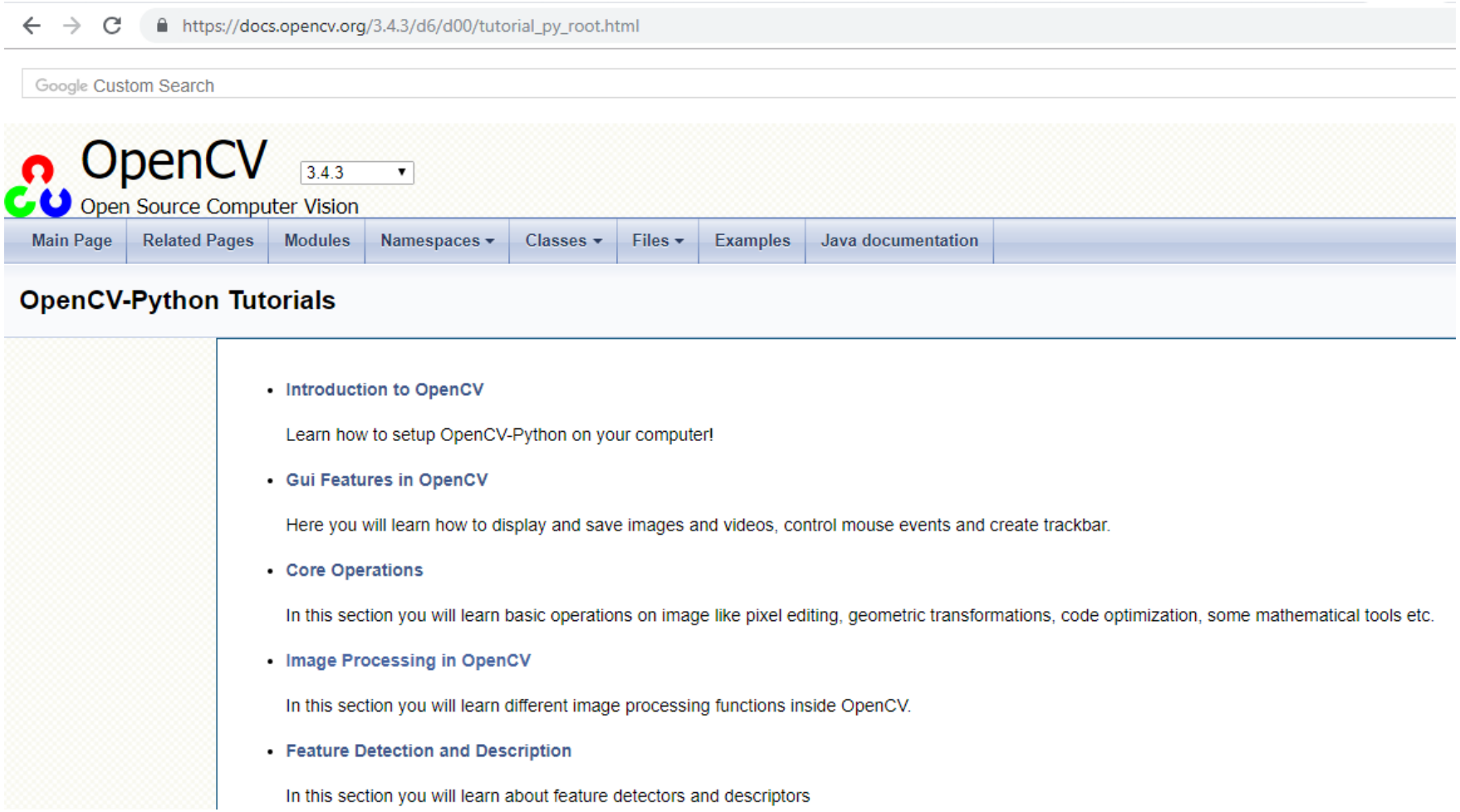
OpenCV 3.4.3 docs



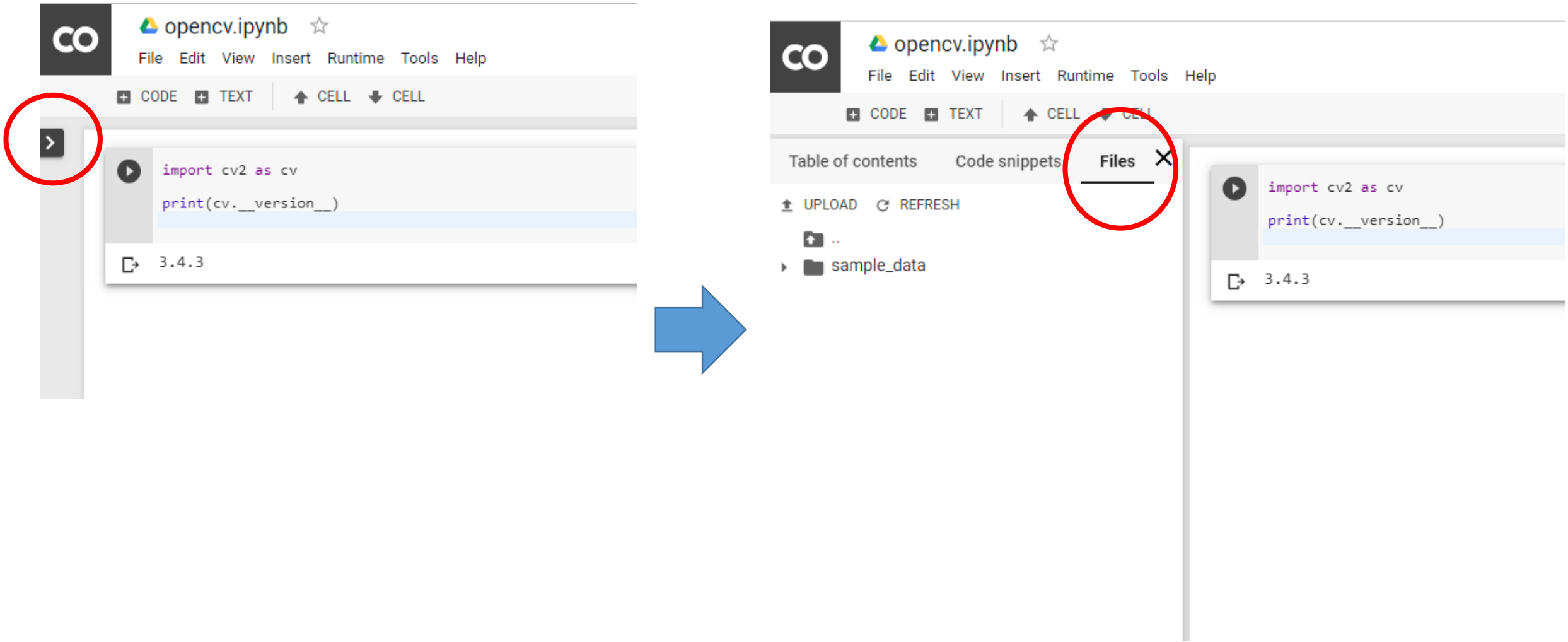
https://docs.opencv.org/3.4.3/

OpenCV-Python Tutorials

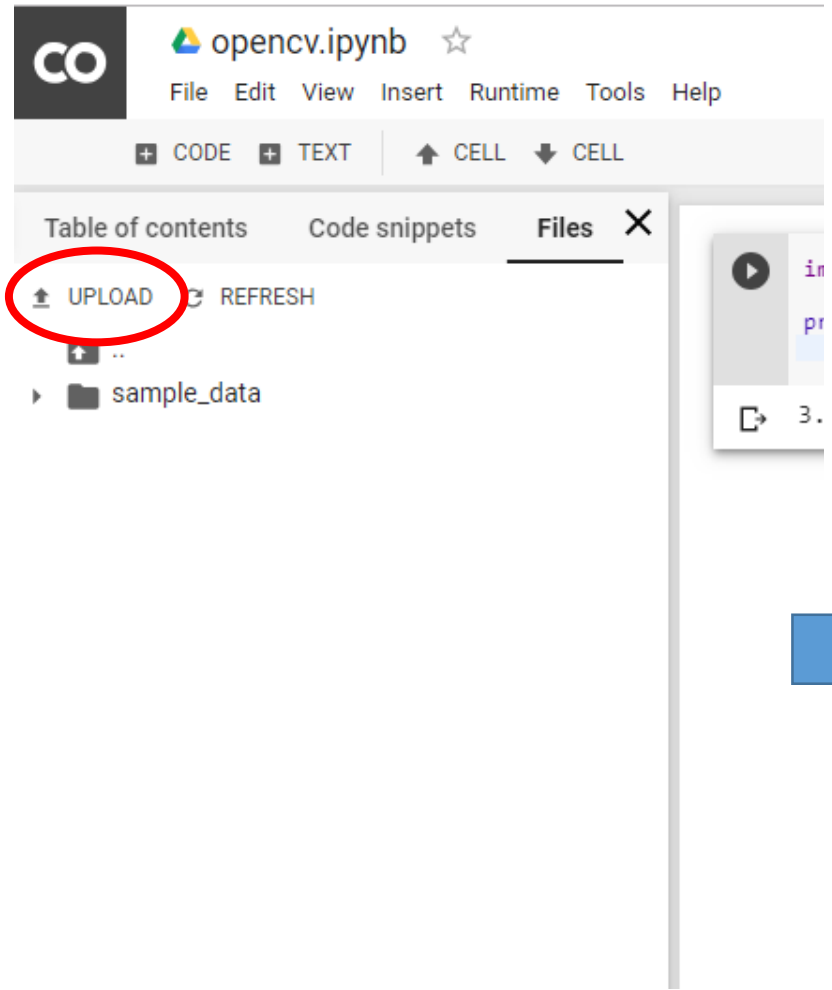
OpenCV fornisce una serie di tutorial specifici per Python che possono essere utilizzati per imparare ad utilizzare la libreria attraverso esempi pratici



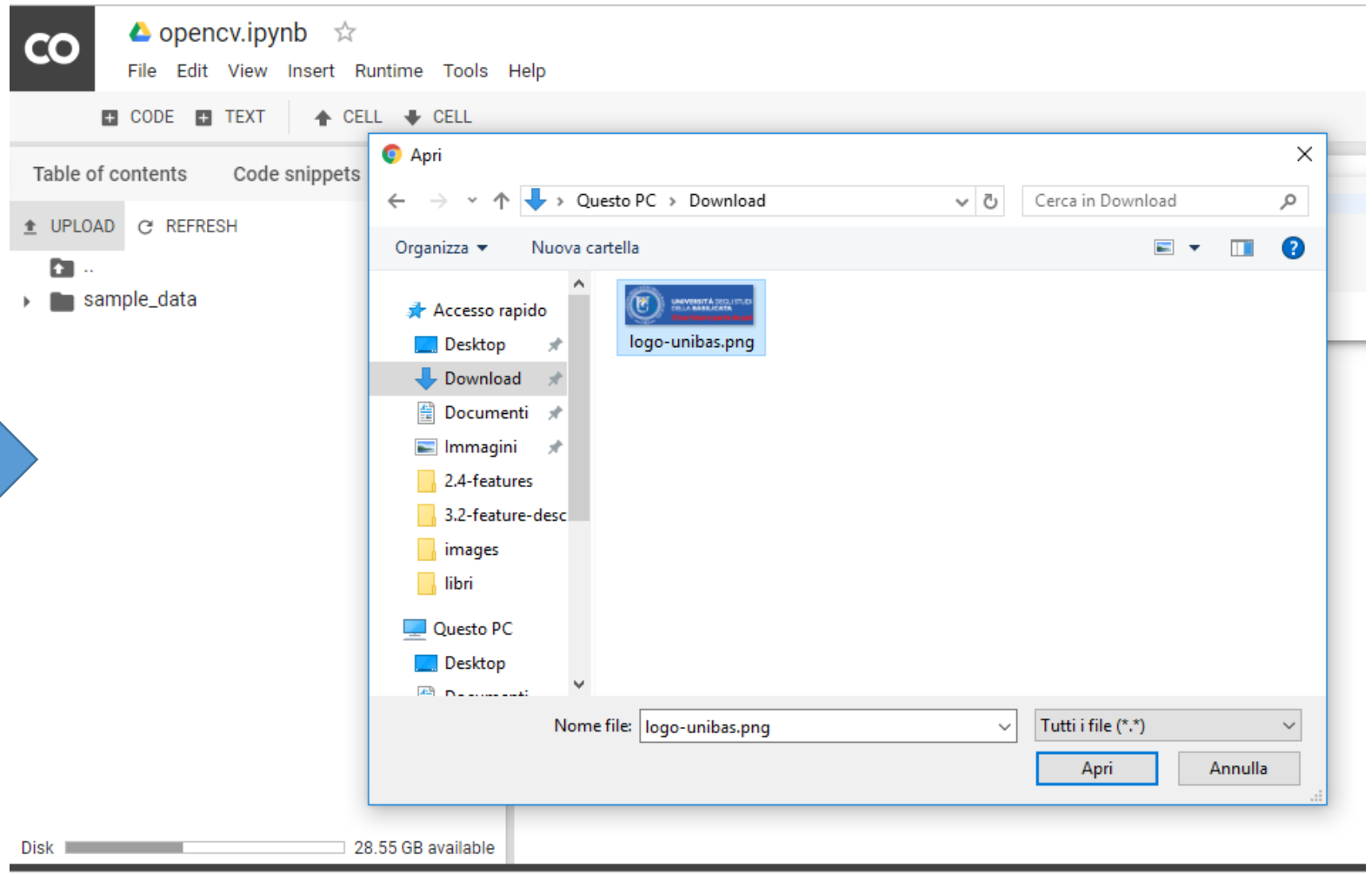
Load an image in Colab



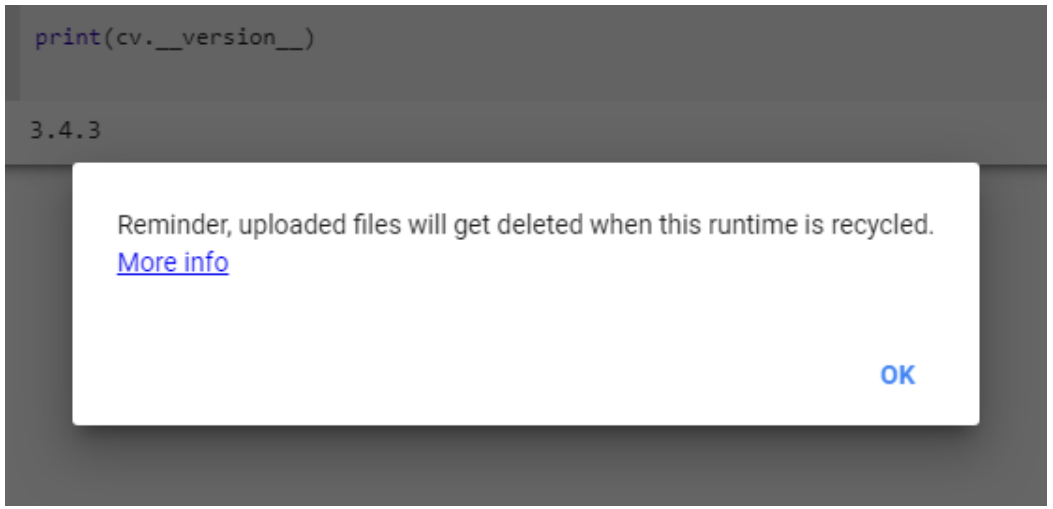
Load an image in Colab

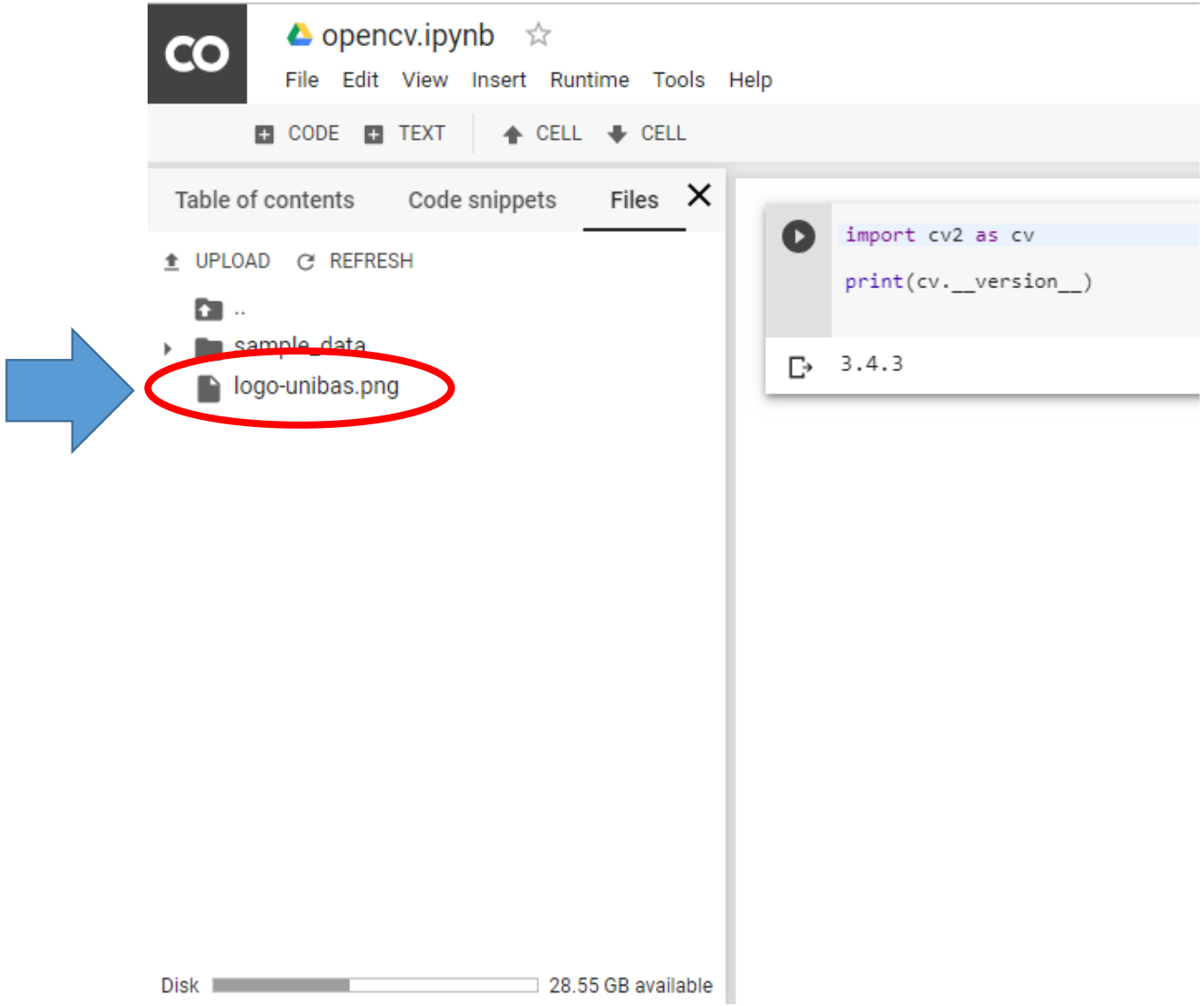


http://portale.unibas.it/contents/instance1/images/logo-unibas.png



Load an image in Colab





Read an image

```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png')
plt.imshow(img)
plt.xticks([]), plt.yticks([])  # to hide tick values on X and Y axis
plt.show()
```

warning
Color image loaded by OpenCV is in **BGR** mode. But Matplotlib displays in RGB mode. So color images will not be displayed correctly in Matplotlib if image is read with OpenCV.

Source image

Images are NumPy arrays

Images in OpenCV-Python are NumPy arrays

```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png')

print(type(img))
print(img.ndim)
print(img.shape)

plt.imshow(img)
plt.xticks([]), plt.yticks([])  # to hide tick values on X and Y axis
plt.show()
```

```
3
(97, 312, 3)
<class 'numpy.ndarray'>
```

RGB visualization in Matplotlib

```python
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

print(type(img))
print(img.ndim)
print(img.shape)

img_rgb = img[:,:,::-1]

plt.imshow(img_rgb)
plt.xticks([]), plt.yticks([])  # to hide tick values on X and Y axis
plt.show()
```

```
<class 'numpy.ndarray'>
3
(97, 312, 3)
```

Accessing and Modifying pixel values

```python
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

# accessing pixel in position (50,100)
px = img[50,100] #[y-value, x-value]
print(px)

# accessing only blue pixel
blue = img[50,100,0]
print(blue)

img[50,100] = [255,255,255]
print(img[50,100])
```

```
[170  92  42]
170
[255 255 255]
```

warning
Numpy is a optimized library for fast array calculations. So simply accessing each and every pixel values and modifying it will be very slow and it is discouraged.

item e itemset

```python
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

# accessing only blue pixel
blue = img.item(50,100,0)
print(blue)

img.itemset((50,100,0),255)
print(img[50,100])
```

```
170
[255  92  42]
```

Accessing Image Properties

number of rows, columns, and channels (if image is color)

```
[28] print(img.shape)
```

```
(97, 312, 3)
```

Total number of pixels

```
[29] print(img.size)
```

```
90792
```

Image datatype

```
print(img.dtype)
```

```
uint8
```

Image ROI

```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

logo = img[0:98,0:98]
img[0:98, 100:198] = logo
img[0:98, 200:298] = logo

img_rgb = img[:,:,::-1]

plt.imshow(img_rgb)
plt.xticks([]), plt.yticks([])  # to hide tick values on X and Y axis
plt.show()
```

Changing Color-space

There are more than 150 color-space conversion methods available in OpenCV.

```
import cv2 as cv
flags = [i for i in dir(cv) if i.startswith('COLOR_')]
print(flags)
print(len(flags))
```

```
['COLOR_BAYER_BG2BGR', 'COLOR_BAYER_BG2BGRA', 'COLOR_BAYER_BG2BGR_EA', 'COLOR_BAYER_BG2BGR_VNG', 'COLOR_BAYER_BG2GRAY'
274
```

Changing Color-space

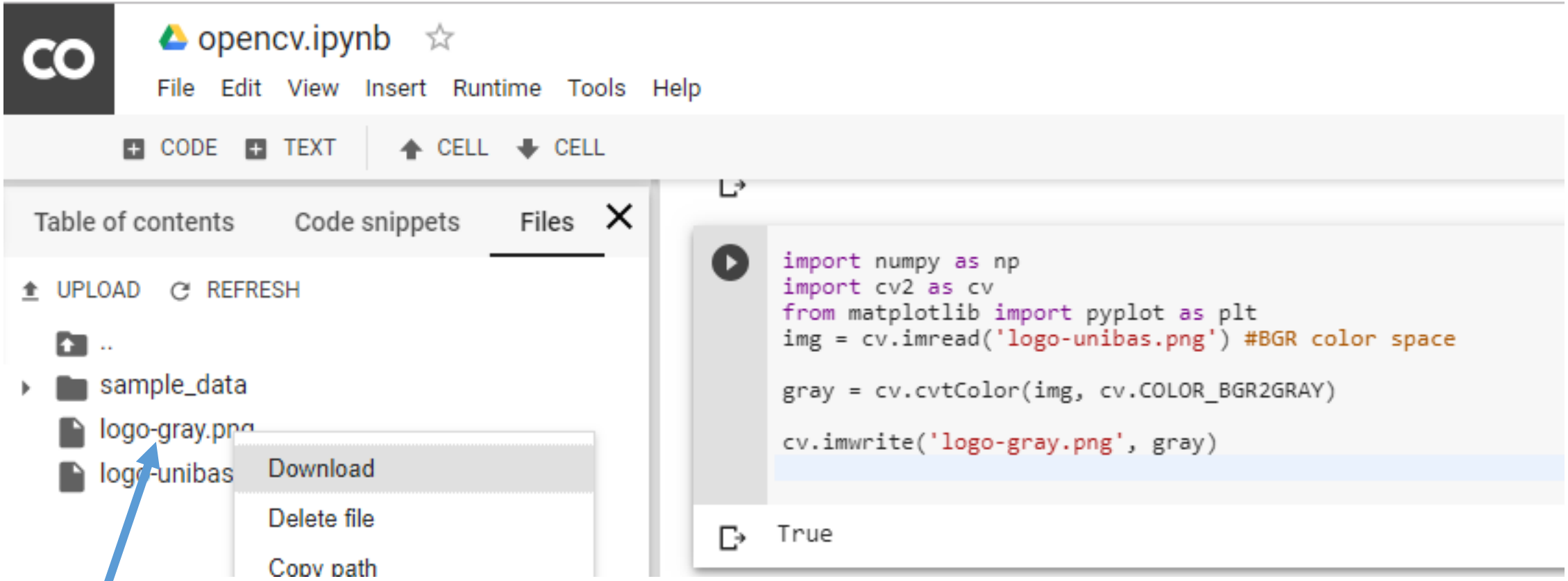
```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

gray = cv.cvtColor(img, cv.COLOR_BGR2GRAY)

cv.imwrite('logo-gray.png', gray)
```

```
True
```

Grayscale conversion



tasto destro del mouse

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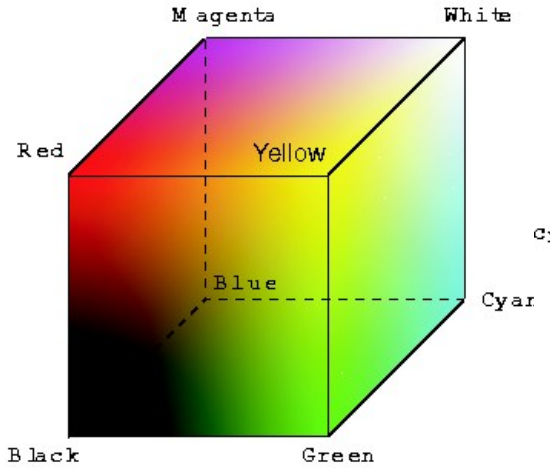
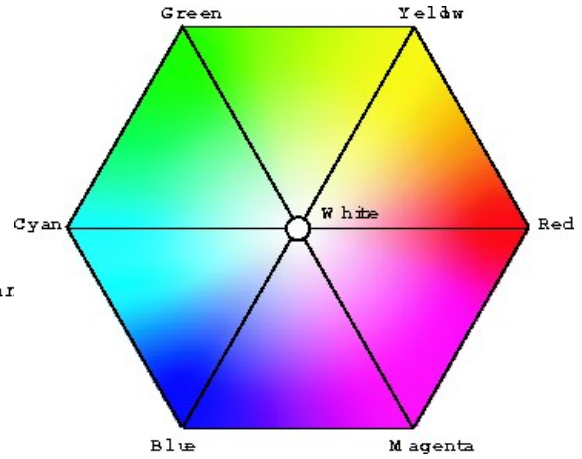
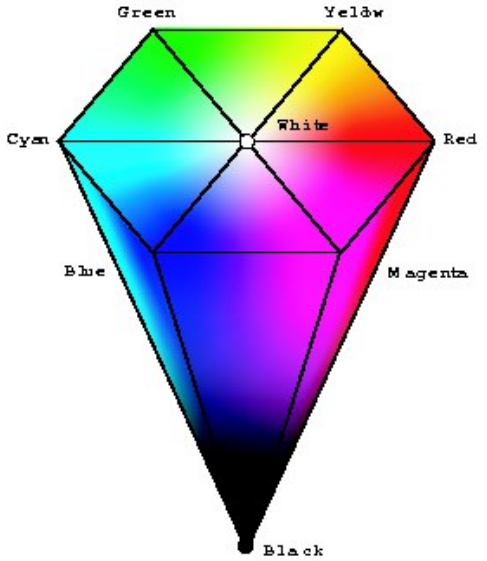
HSV color-space



RGB cube



HSV top view

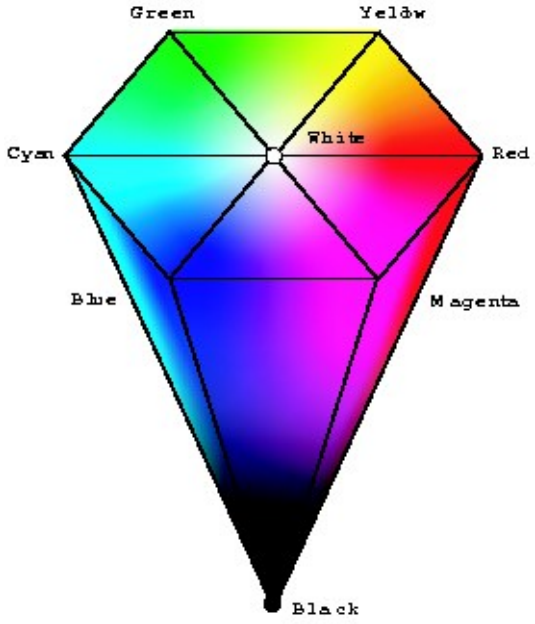


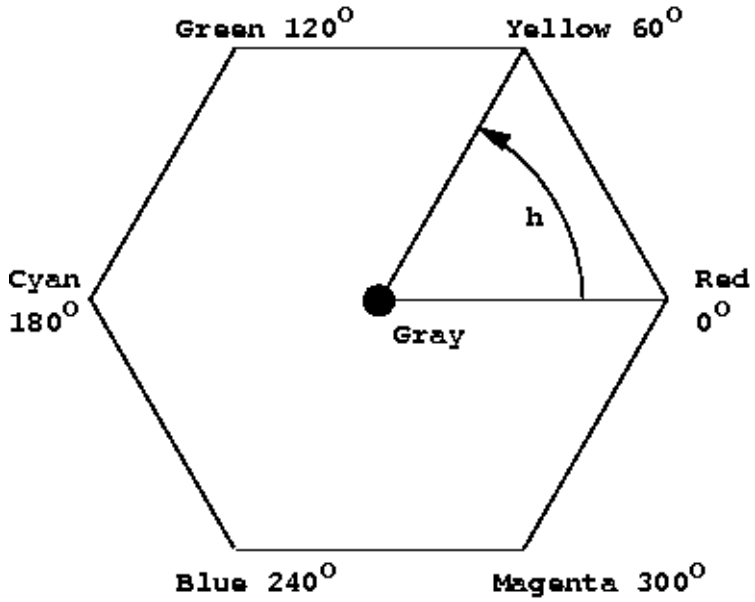
HSV cone

HSV is a projection of the RGB space

Source: Donald House

Hue



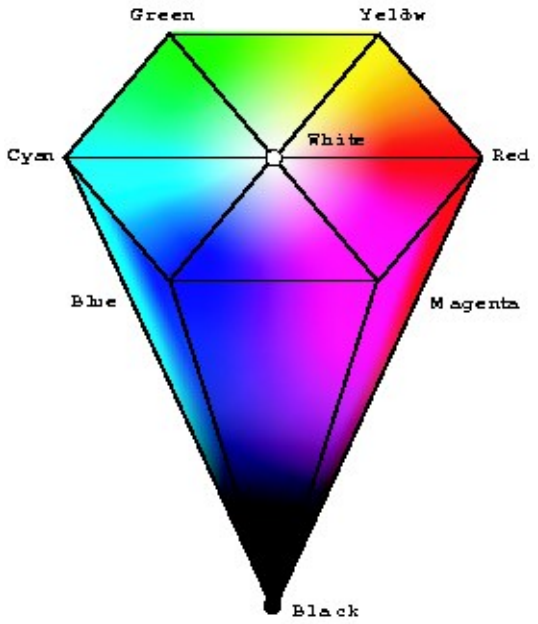


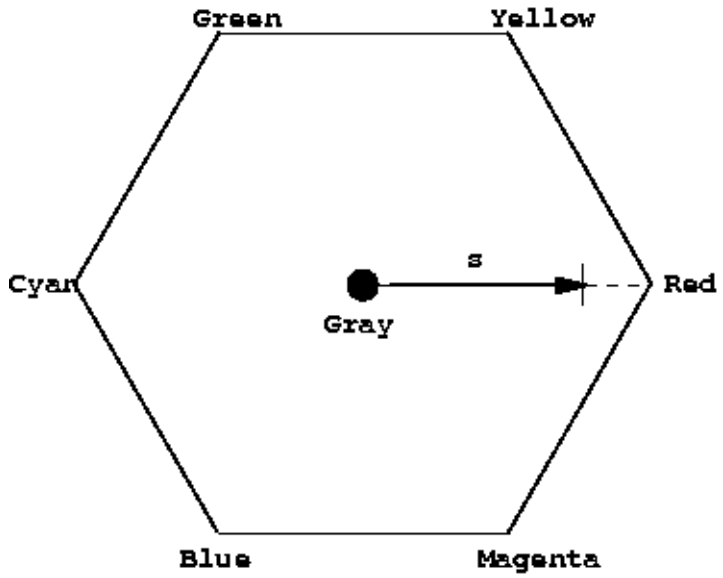
Hue, an angular measure (0 … 360)

Hue range is [0,179] in OpenCV

Source: Donald House

Saturation



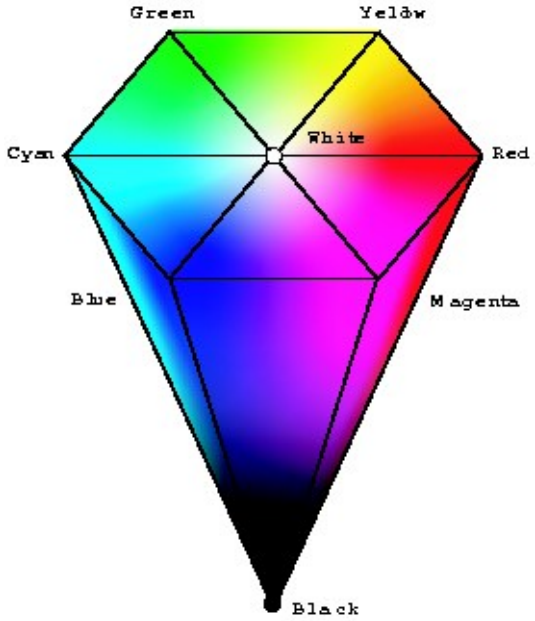


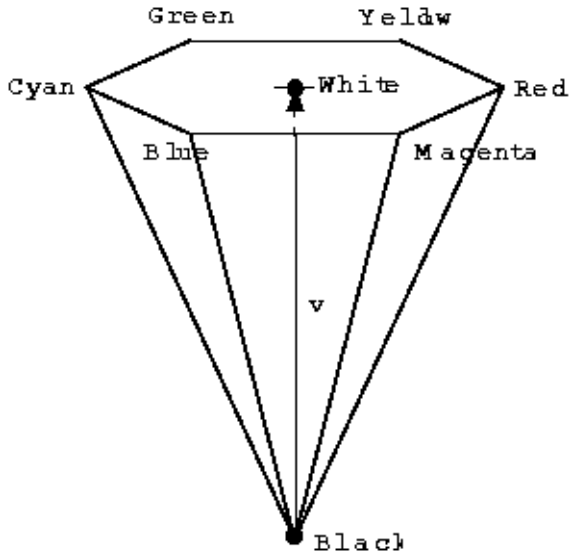
Saturation, a fractional measure (0.0 … 1.0)

Saturation range is [0,255] in OpenCV

Source: Donald House

Value





Value, a fractional measure (0.0 … 1.0)

Value range is [0,255] in OpenCV

Source: Donald House

HSV conversion

```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

hsv = cv.cvtColor(img, cv.COLOR_BGR2HSV)

plt.imshow(hsv)
plt.xticks([]), plt.yticks([])  # to hide tick values on X and Y axis
plt.show()
```

Split

```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

hsv = cv.cvtColor(img, cv.COLOR_BGR2HSV)

h,s,v = cv.split(hsv)

plt.imshow(h)
plt.xticks([]), plt.yticks([])  # to hide tick values on X and Y axis
plt.show()
```

Split – Saturation channel

```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

hsv = cv.cvtColor(img, cv.COLOR_BGR2HSV)

h,s,v = cv.split(hsv)

plt.imshow(s)
plt.xticks([]), plt.yticks([])  # to hide tick values on X and Y axis
plt.show()
```

Split – Value channel

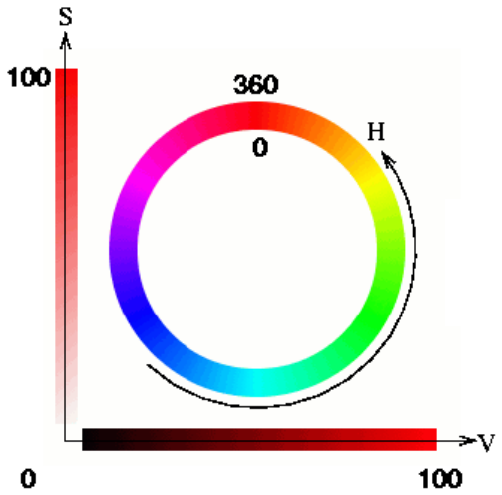
```
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

hsv = cv.cvtColor(img, cv.COLOR_BGR2HSV)

h,s,v = cv.split(hsv)

plt.imshow(s)
plt.xticks([]), plt.yticks([])  # to hide tick values on X and Y axis
plt.show()
```

Merge

```python
import numpy as np
import cv2 as cv
from matplotlib import pyplot as plt
img = cv.imread('logo-unibas.png') #BGR color space

hsv = cv.cvtColor(img, cv.COLOR_BGR2HSV)

h,s,v = cv.split(hsv)

hsv_merged = cv.merge((h,s,v))

plt.imshow(hsv_merged)
plt.xticks([]), plt.yticks([])  # to hide tick values on X and Y axis
plt.show()
```

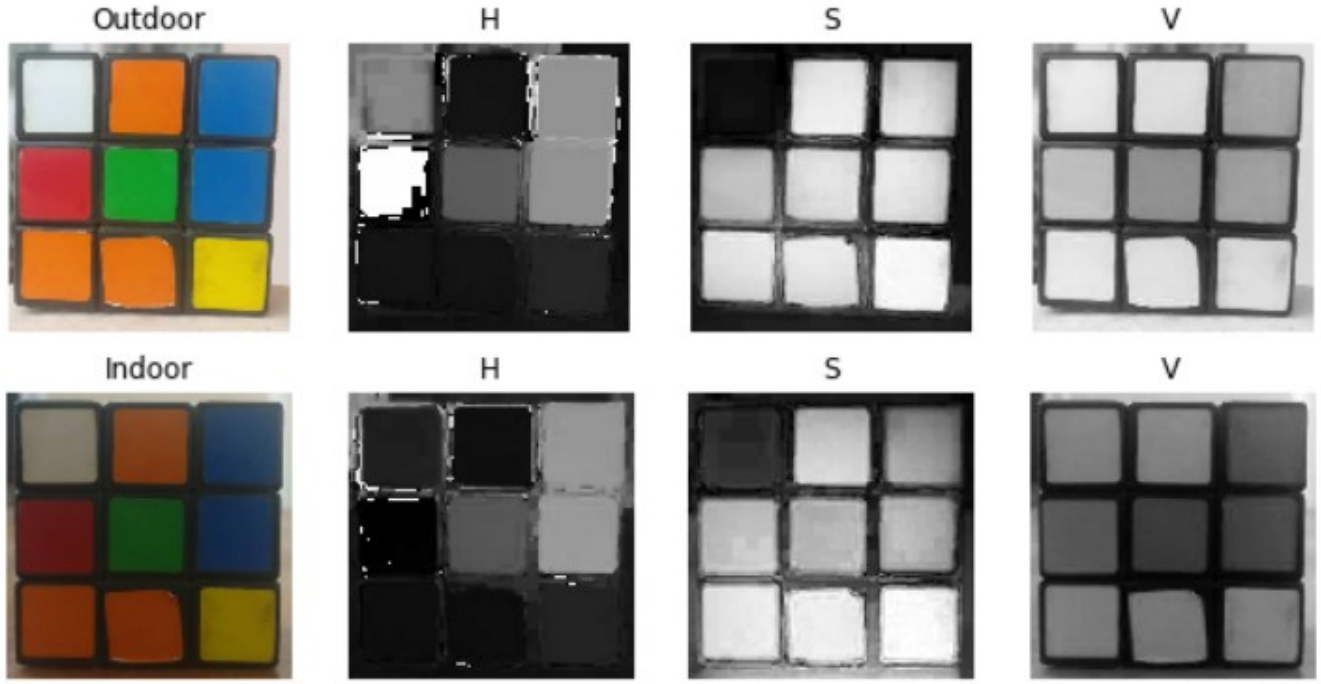
HSV color space

http://tinf2.vub.ac.be/~dvermeir/manual/gimp/Grokking-the-GIMP-v1.0/node51.html



The HSV color space has the following three components

1. H – Hue (Dominant Wavelength)
2. S – Saturation (Purity/shades of the color)
3. V – Value (Intensity)



Observations

- The H Component is very similar in both the images which indicates the color information is intact even under illumination changes
- The S component is also very similar in both images
- The V Component captures the amount of light falling on it thus it changes due to illumination changes

https://www.learnopencv.com/color-spaces-in-opencv-cpp-python/

Read an image from URL

```
import numpy as np
import cv2 as cv

import matplotlib.pyplot as plt
import urllib.request

url = "http://portale.unibas.it/contents/instance1/images/logo-unibas.png"
url_response = urllib.request.urlopen(url)

numpy_img = np.array(bytearray(url_response.read()), dtype=np.uint8)
img = cv.imdecode(numpy_img, -1)

plt.imshow(img)
plt.xticks([]), plt.yticks([])  # to hide tick values on X and Y axis
plt.show()
```

Read an image from URL

```
import cv2 as cv
import numpy as np
import matplotlib.pyplot as plt
import urllib.request

url = "http://portale.unibas.it/contents/instance1/images/logo-unibas.png"

url_response = urllib.request.urlopen(url)
numpy_img = np.array(bytearray(url_response.read()), dtype=np.uint8)
img = cv.imdecode(numpy_img, -1)

rgb = cv.cvtColor(img,cv.COLOR_BGR2RGB)

plt.axis('off')
plt.imshow(rgb)
plt.show()
```



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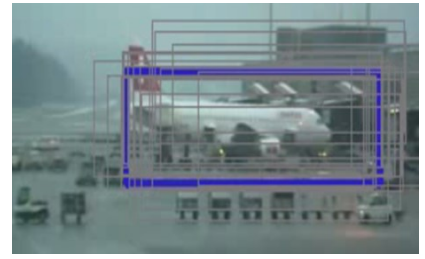

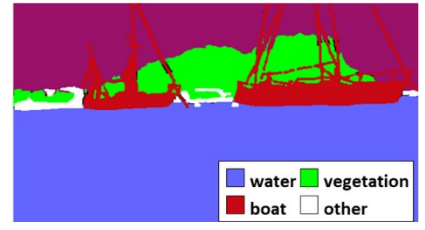

OpenCV (Python)

Aprile 2019